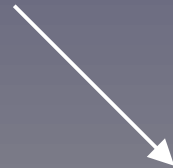


Recognition of Car License Plates using a Neocognitron type of Artificial Neural Network

Introduction



universal
character
reader

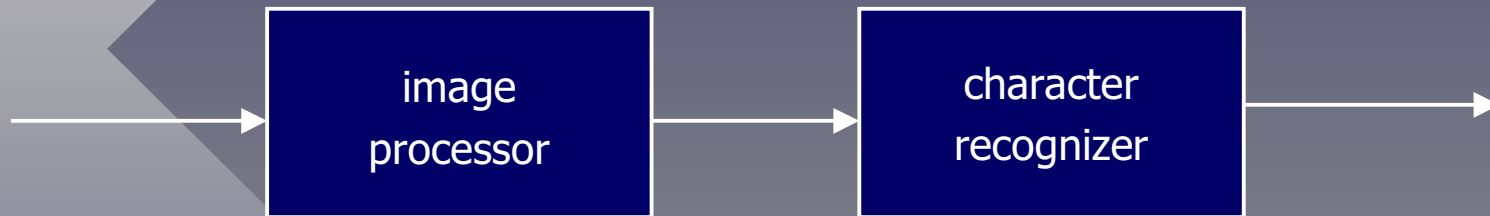


XNZD18

CRXU 121407

Introduction

The basic model



- Image processor
 - finding and selecting all possible character images at any location, from any size from any color
- Character recognizer
 - classifying all character images, with any style/font

Introduction

Scope limitation



- Image processor
 - traditional programming using a license plate definition
- Character recognizer
 - neural computing using a neocognitron

Presentation

Contents

- | | |
|------------------------|-------------|
| 1. Image processor | (5 sheets) |
| 2. Neocognitron theory | (8 sheets) |
| 3. Application in CLPR | (8 sheets) |
| 4. CLPR system | (5 sheets) |
| 5. Conclusion | (1 sheet) |
| Demonstration | (5 minutes) |

Image processing

- What: Finding the possible characters
- How: Image transformations
- Not: Using explicit knowledge

Finding the plate characters



Original image



Contrast stretched



Filtered

Finding the plate characters



Original image



Contrast stretched



Filtered



Binarized

Finding the plate characters



Original image



Contrast stretched



Filtered



Binarized



Area filled

Finding the plate characters



Original image



Contrast stretched



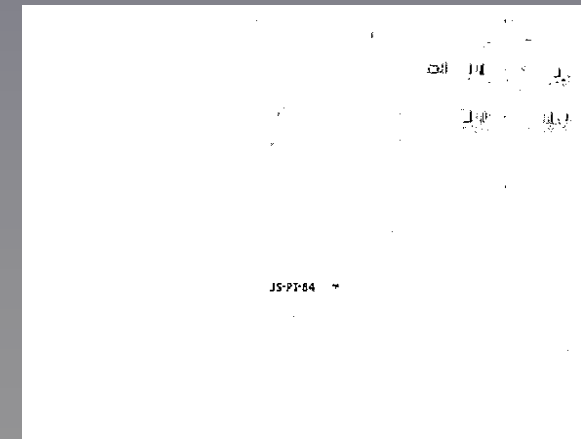
Filtered



Binarized



Area filled



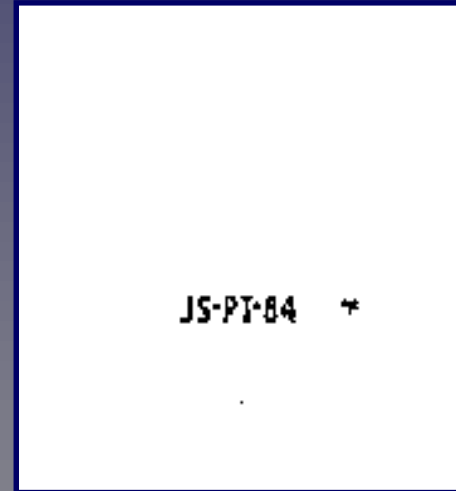
Pre-processed

Catching the segments

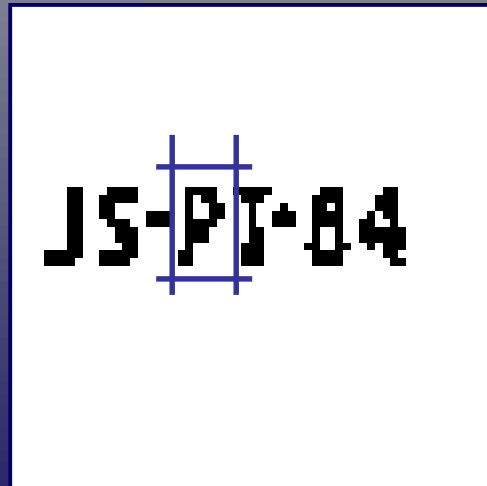
Original picture



Processed picture



Segment Location

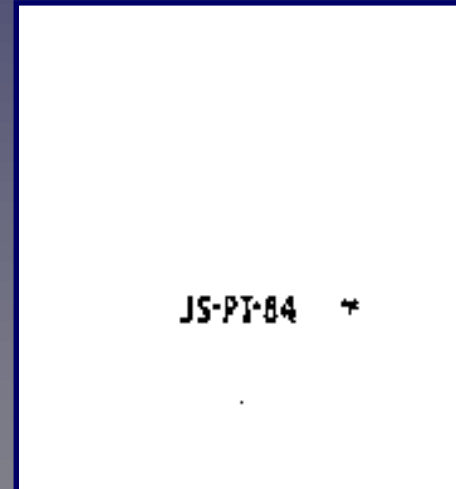


Catching the segments

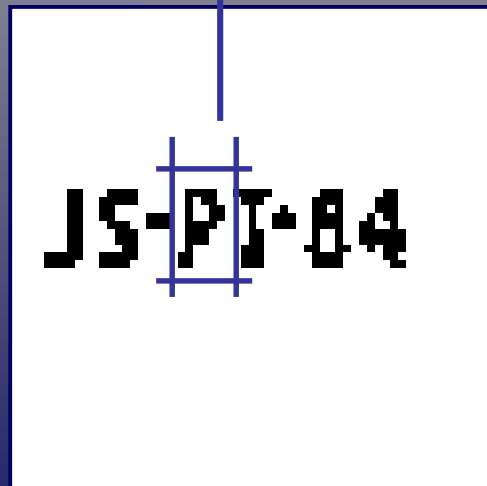
Original picture



Processed picture

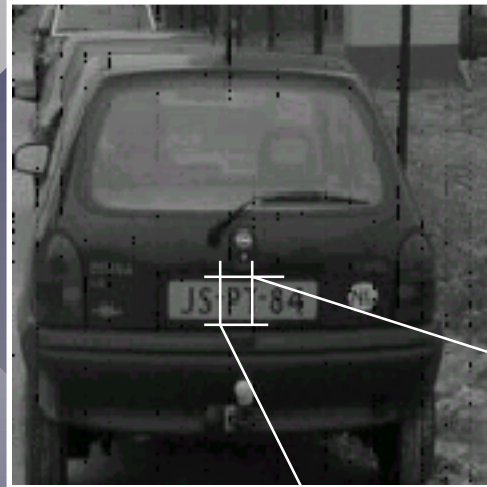


Segment Location

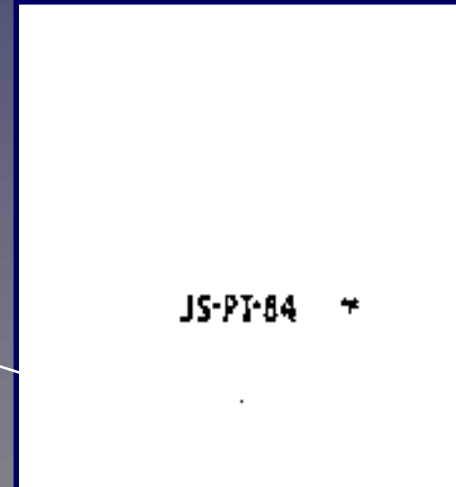


Catching the segments

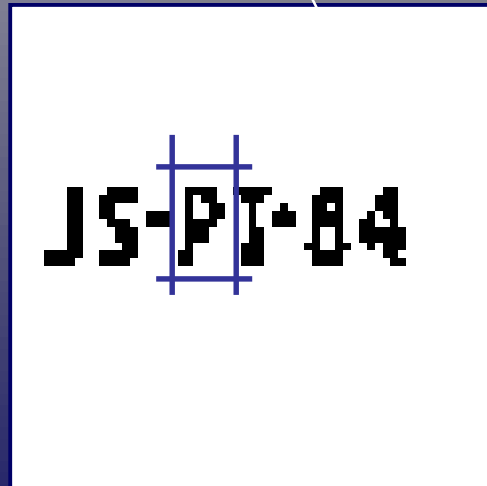
Original picture



Processed picture



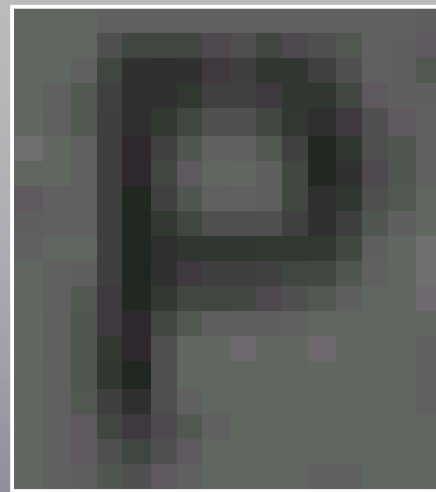
Segment Location



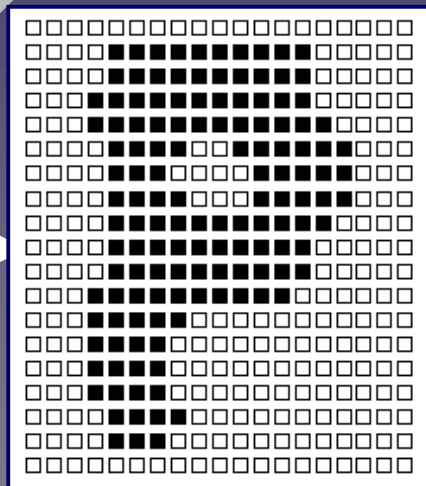
Isolated segment



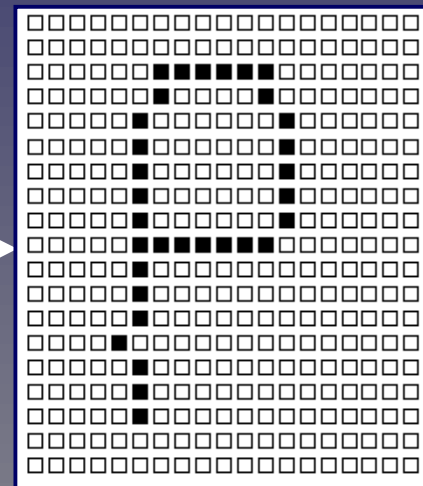
Formatting the segments



Magnify



Binarize Segment



Thin Segment

To
Neocognitron

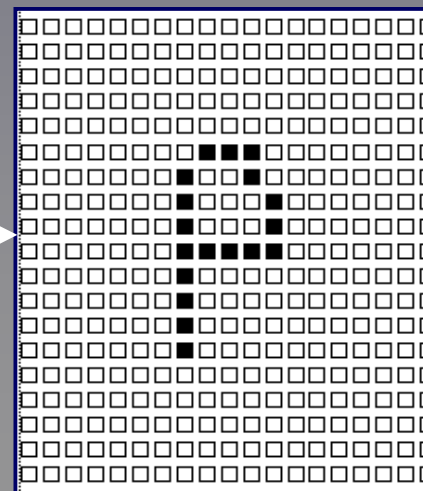
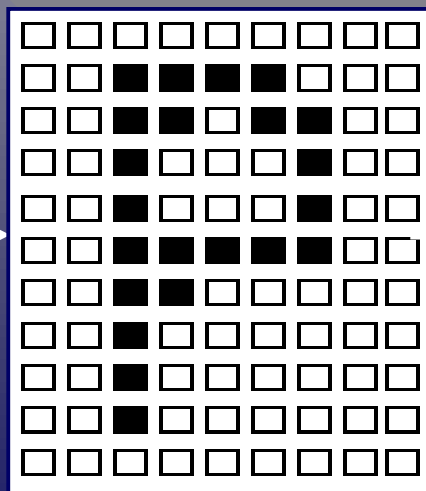


Image-processor's generality



Image-processor's generality

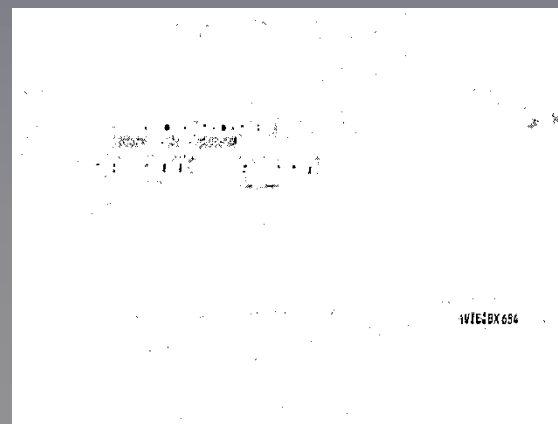
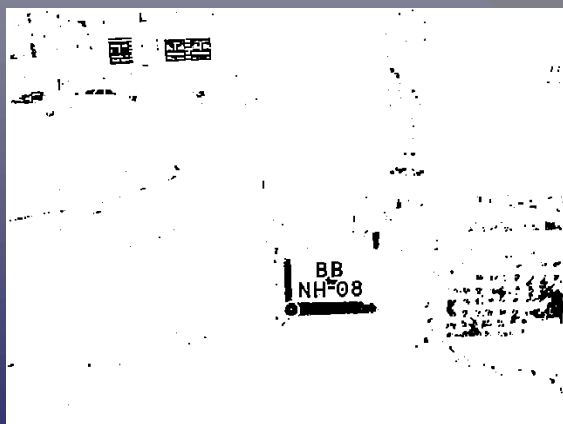
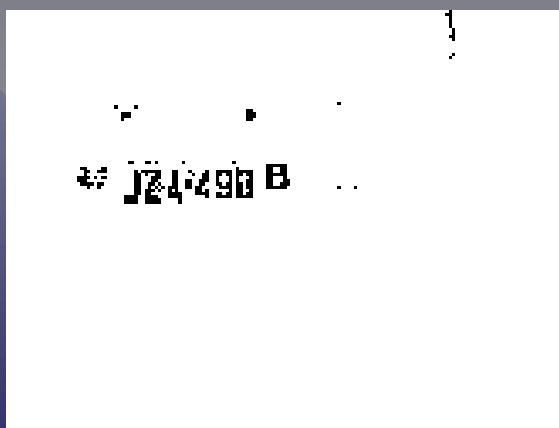
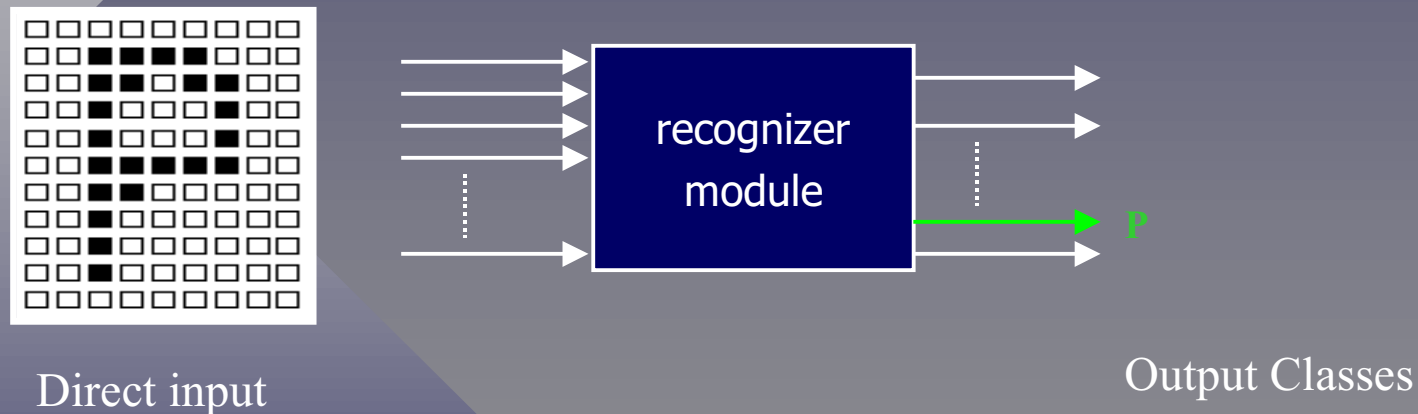


Image-processor's generality



Character recognizer

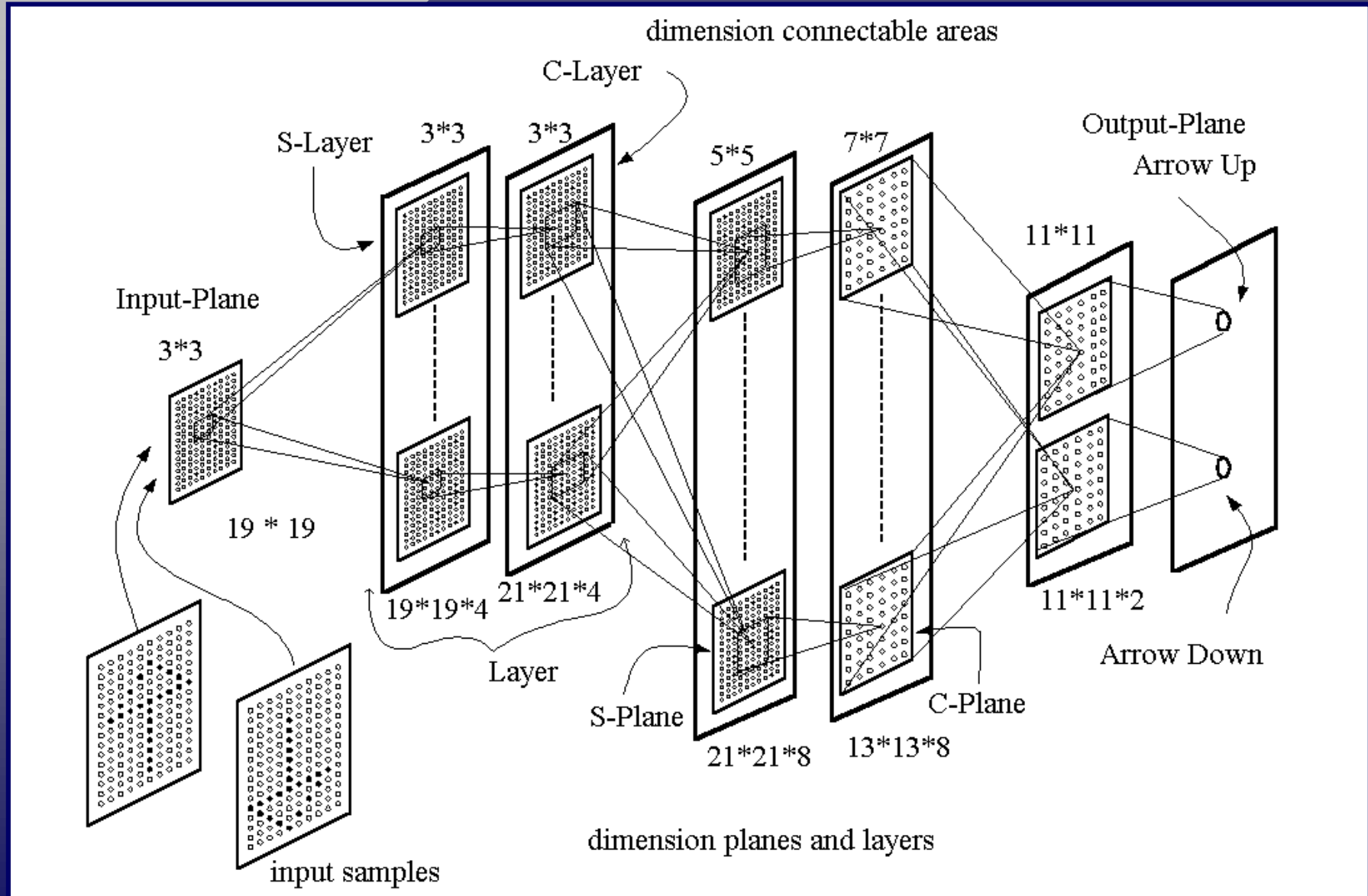
- What: Classify the isolated image segments.



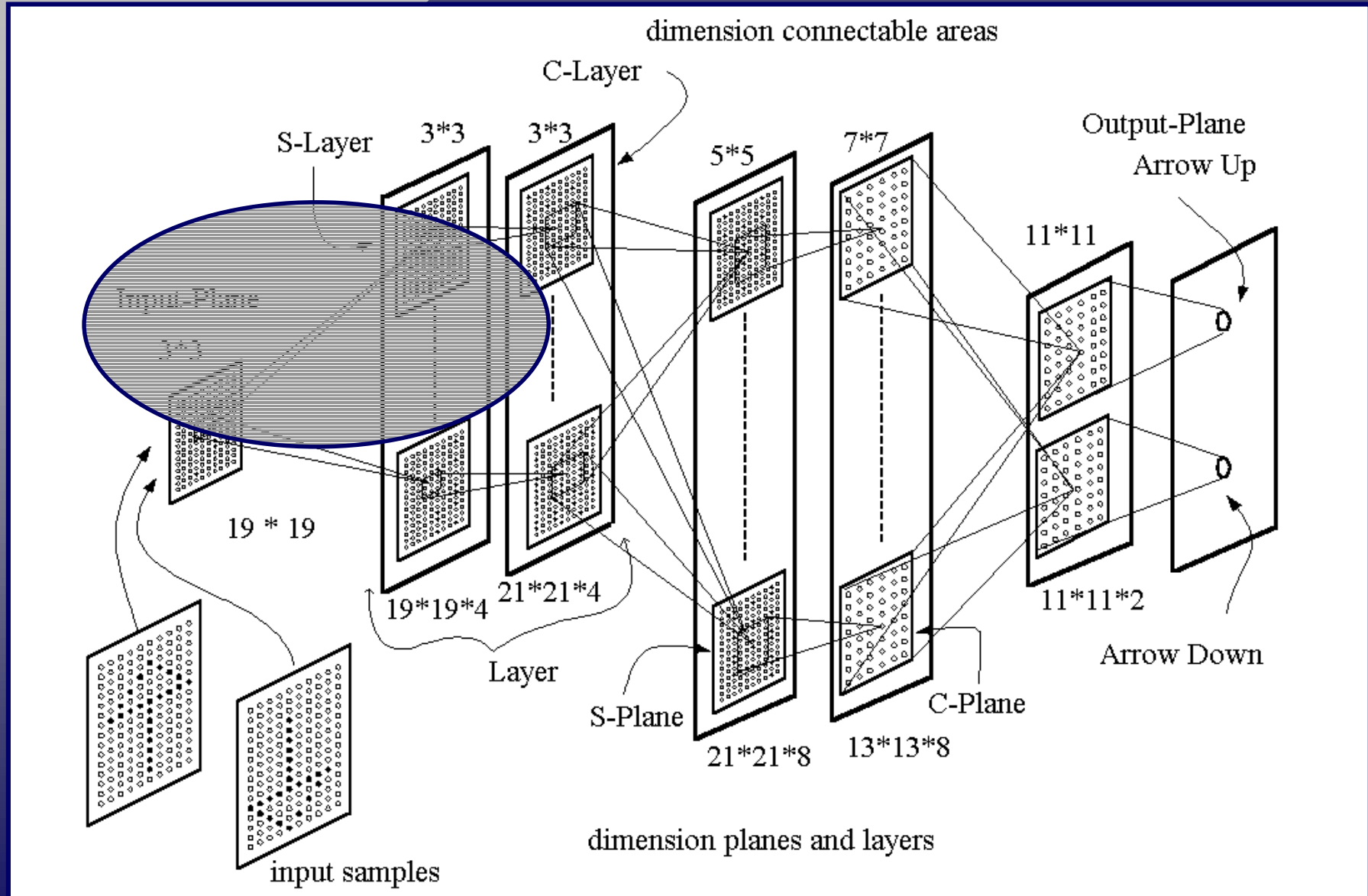
- How: Using a function from char-image \rightarrow char-class

$$f : R^N \rightarrow R^M$$

Neocognitron network layout example.

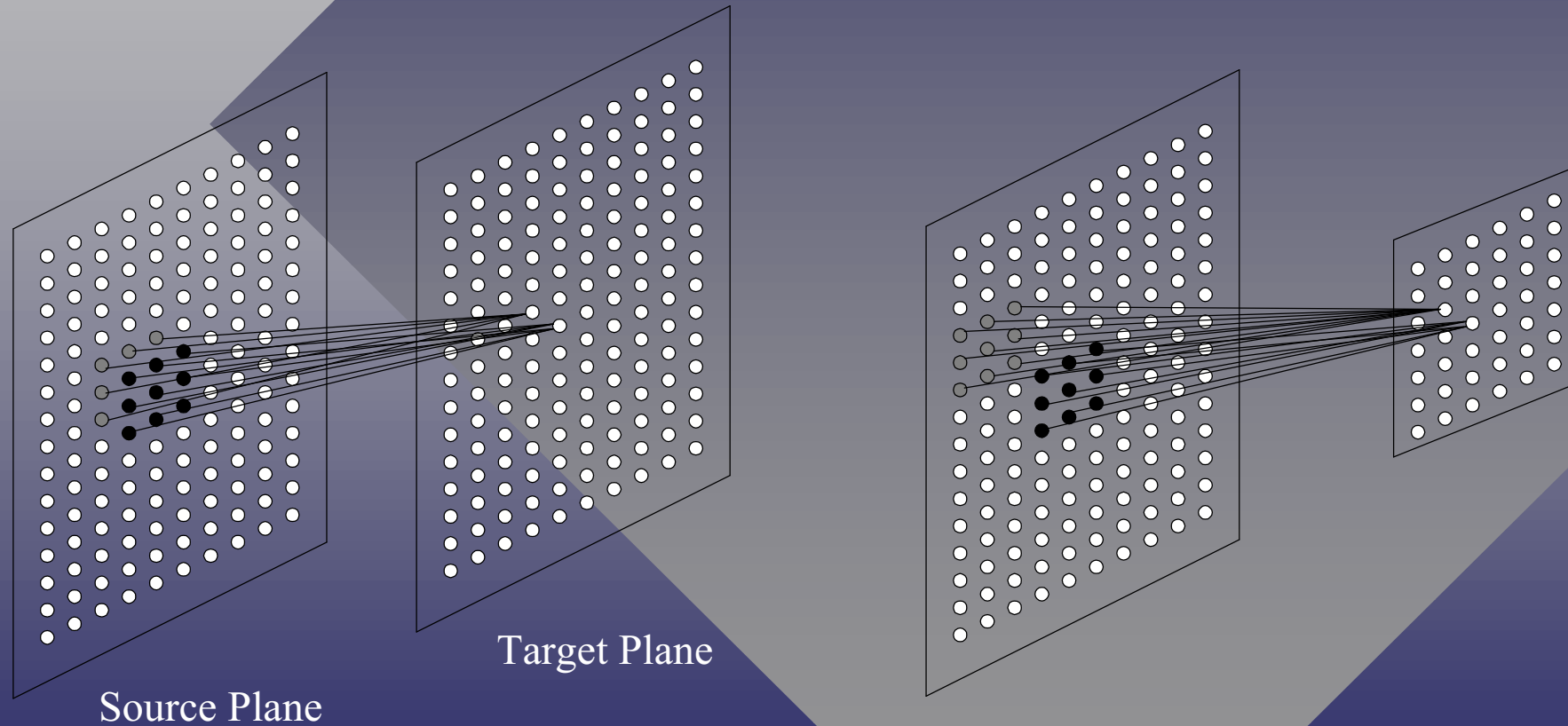


Neocognitron network layout example.



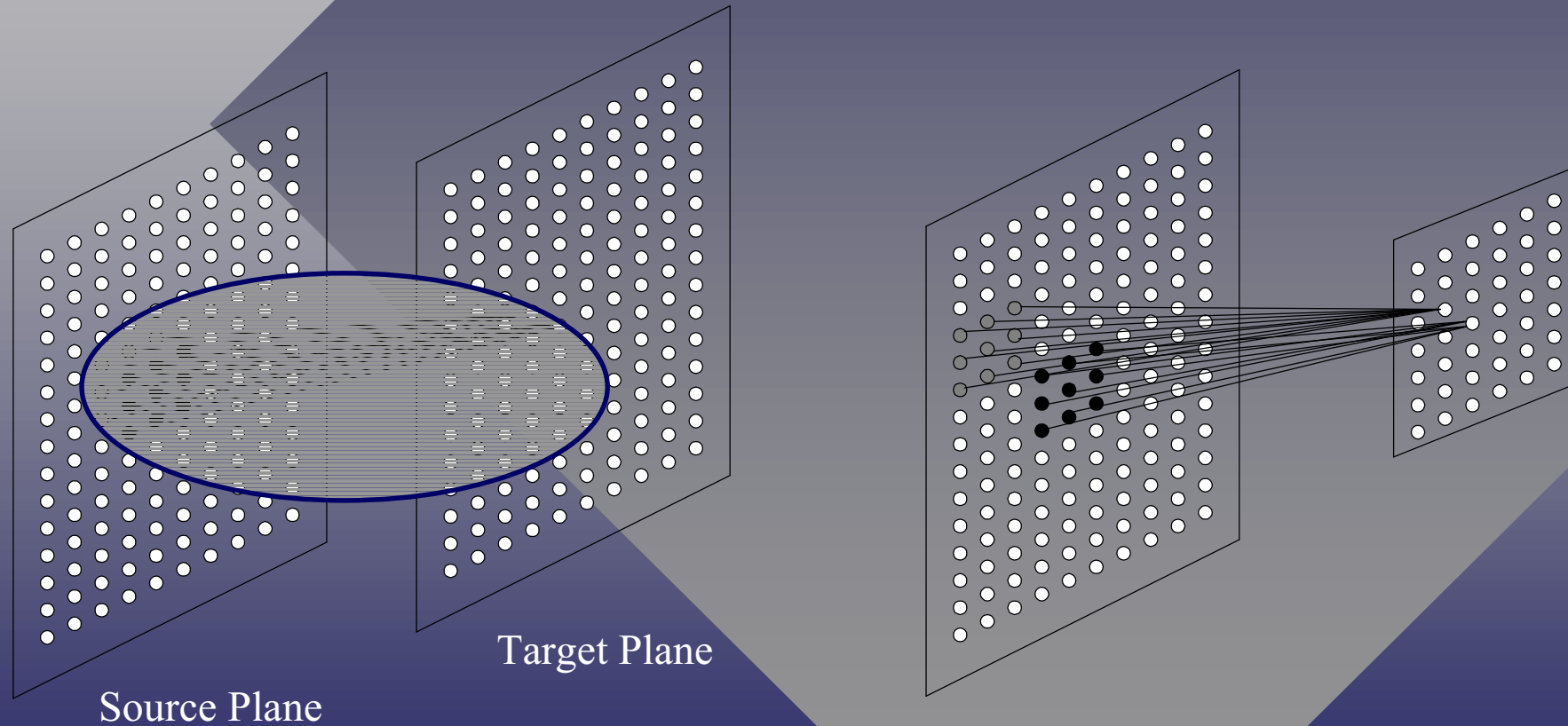
Neocognitron network

plane-connections.

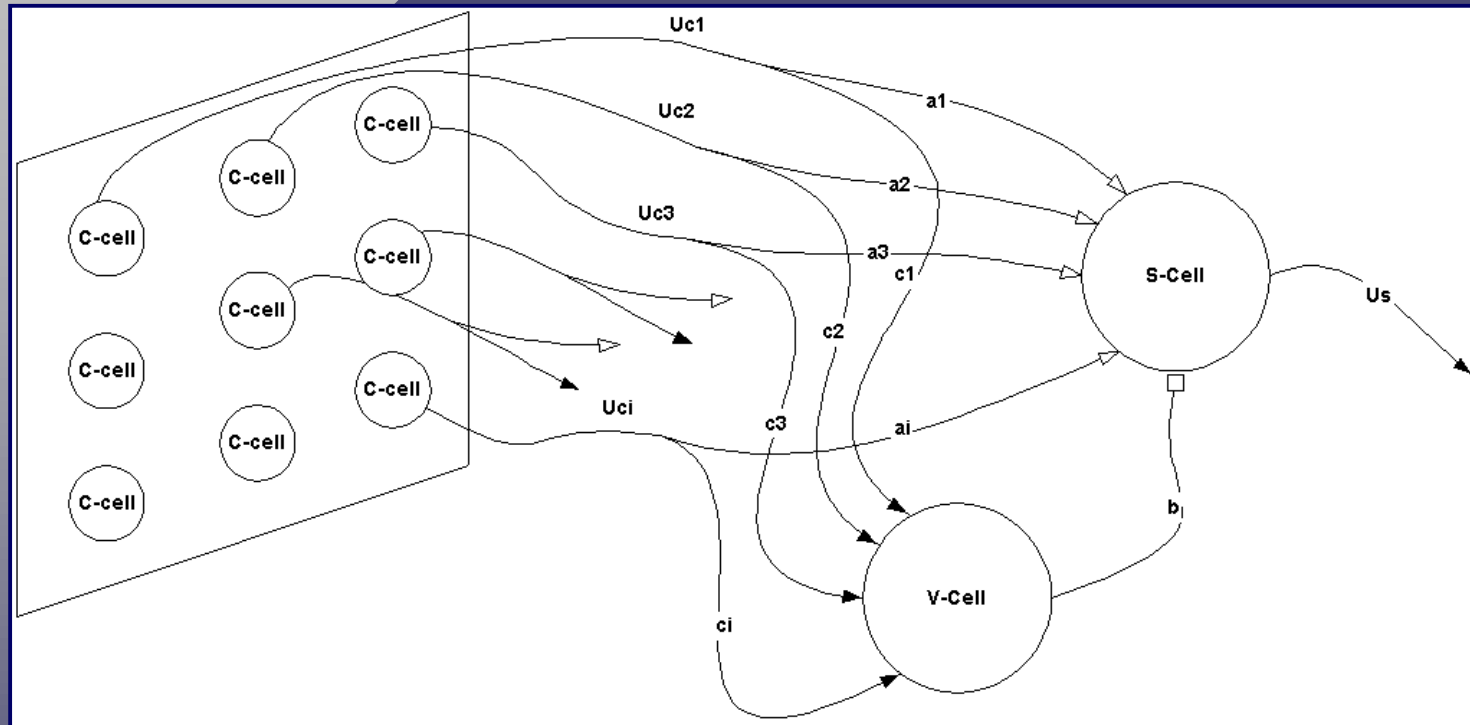


Neocognitron network

plane-connections.



Neocognitron network. cell-connections.



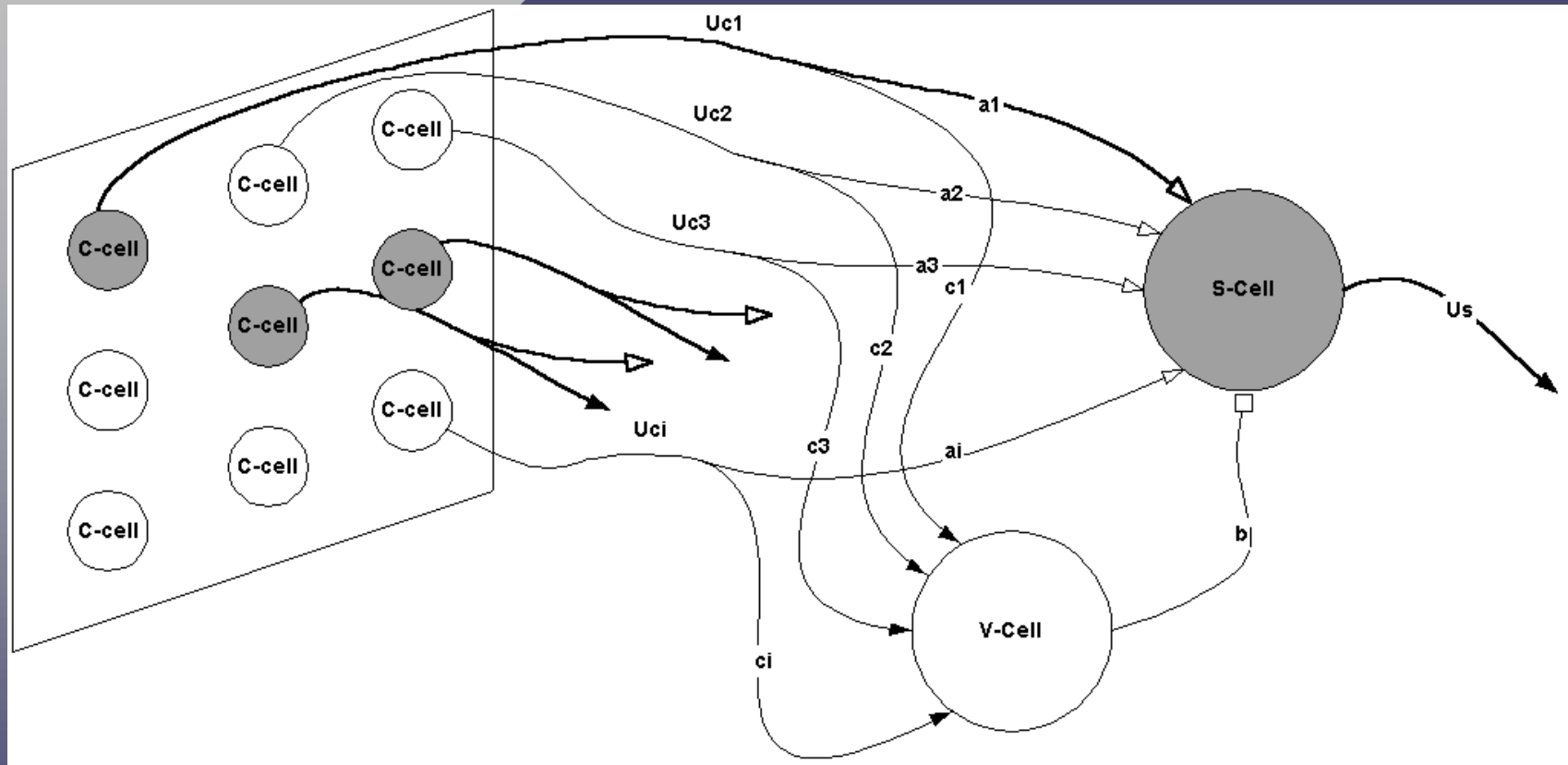
$$Uv = \sqrt{\sum_{i \in A} c_i U^2 c_i}$$

$$c_\lambda(v) = \gamma_\lambda^{|v|}$$

$$Us = r \varphi \left[\frac{1 + \sum_{i \in A} a_i U c_i}{1 + \frac{r}{r+1} b U v} - 1 \right]$$

Neocognitron network.

cell-connections.

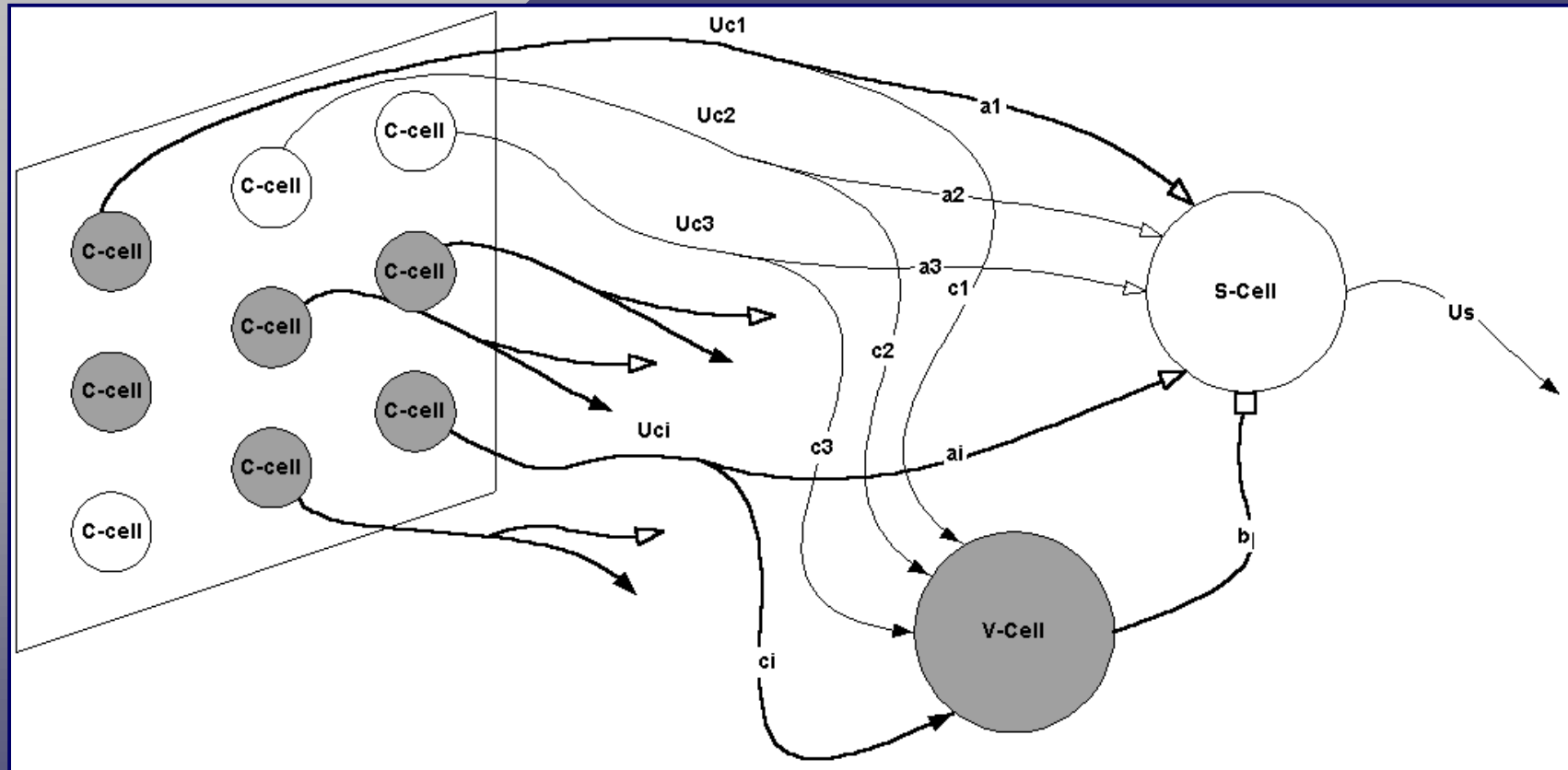


$$U_v = \sqrt{\sum_{i \in A} c_i U^2 c_i}$$

$$U_s = r \varphi \left[\frac{1 + \sum_{i \in A} a_i U c_i}{1 + \frac{r}{r+1} b U_v} - 1 \right]$$

$$c_\lambda(v) = \gamma_\lambda^{|v|}$$

Neocognitron network. cell-connections.



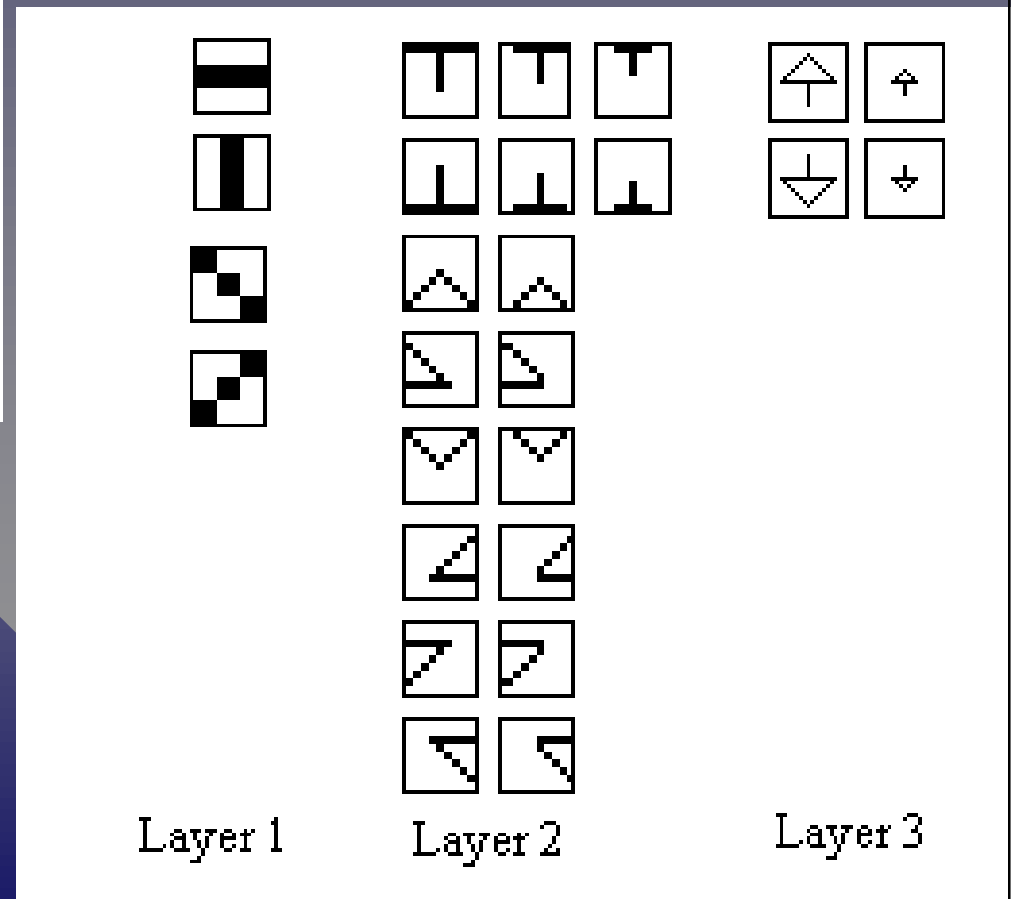
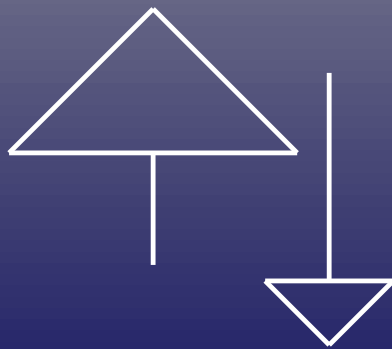
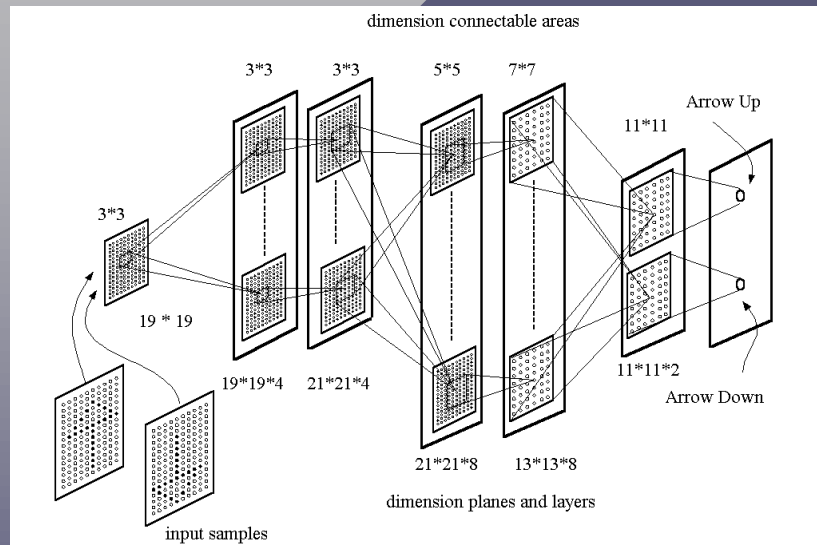
$$Uv = \sqrt{\sum_{i \in A} c_i U^2 c_i}$$

$$c_\lambda(v) = \gamma_\lambda^{|v|}$$

$$Us = r\varphi \left[\frac{1 + \sum_{i \in A} a_i U c_i}{1 + \frac{r}{r+1} b U v} - 1 \right]$$

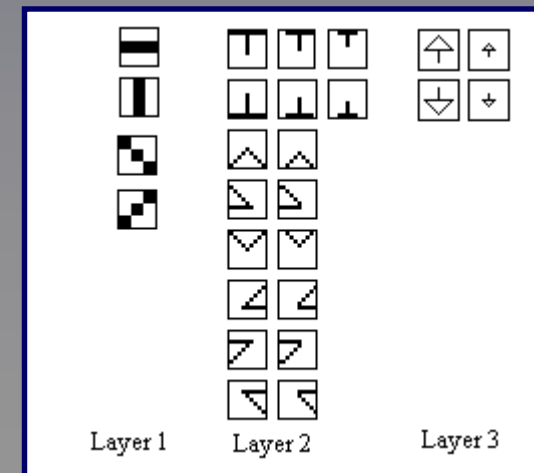
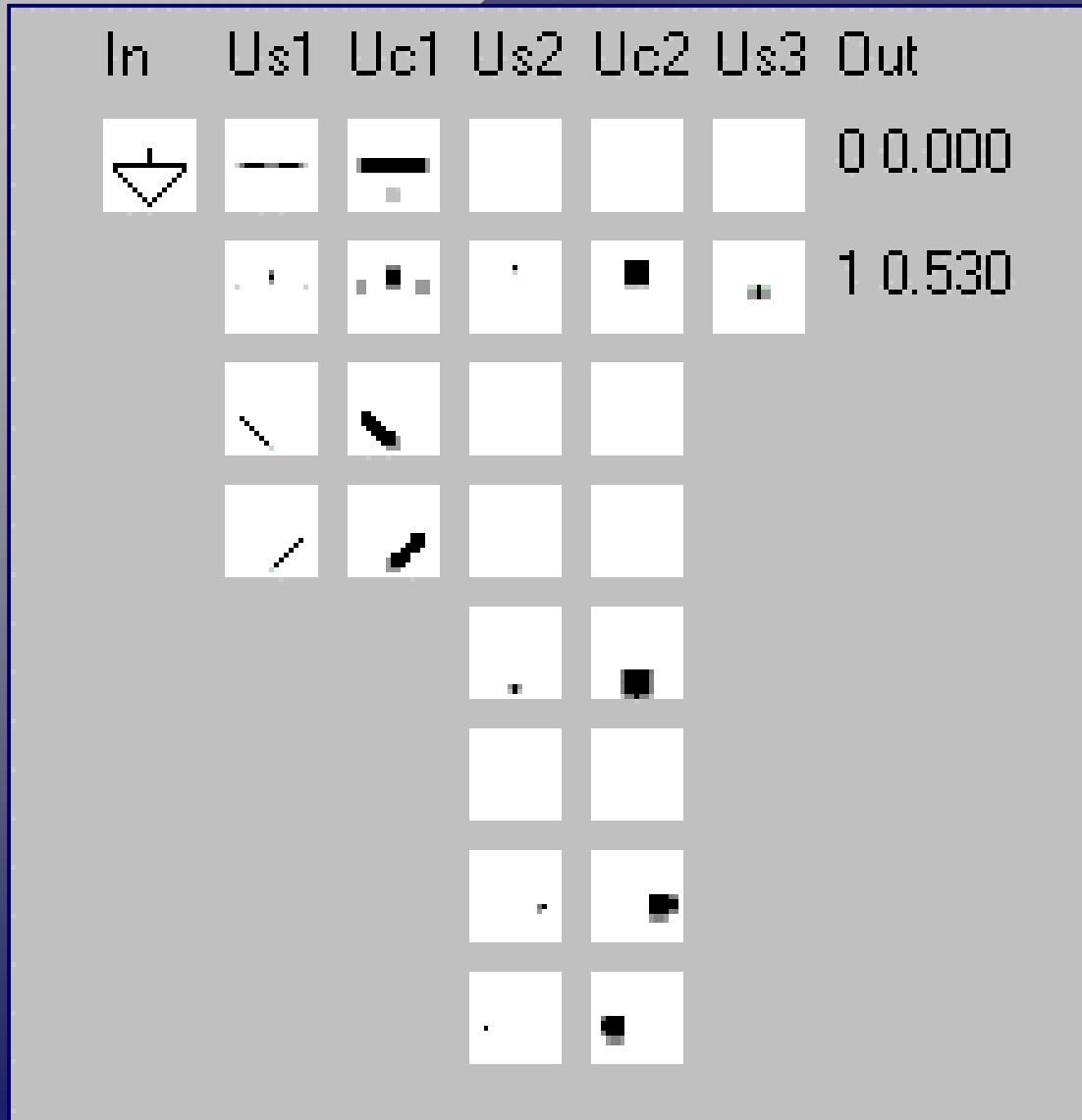
Neocognitron network.

training-set for recognition of *arrow* images.



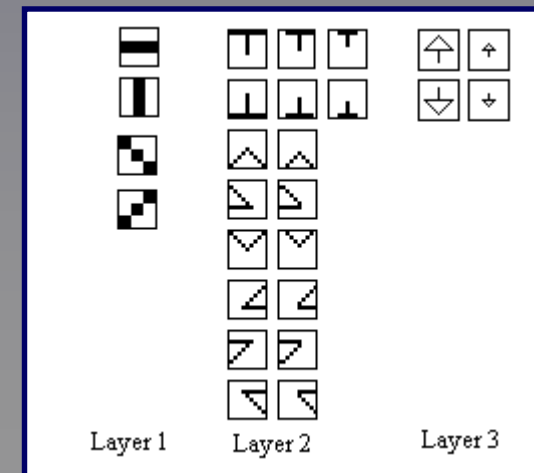
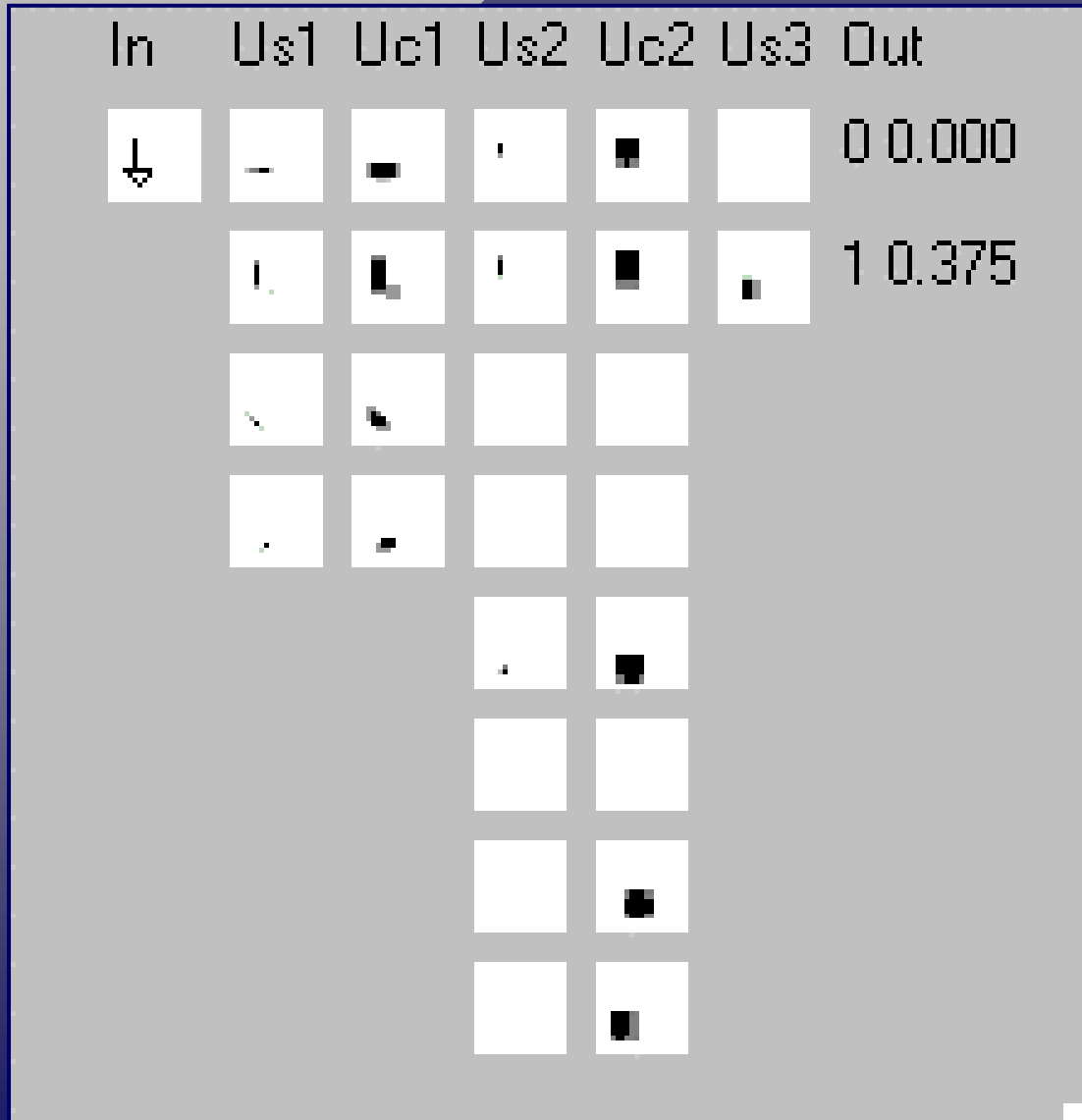
Neocognitron network.

network response on *arrow* images.



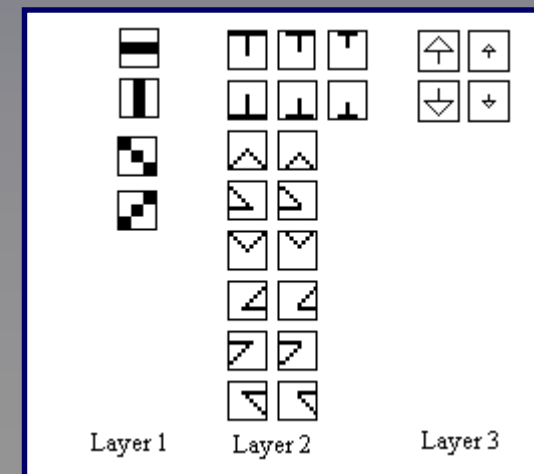
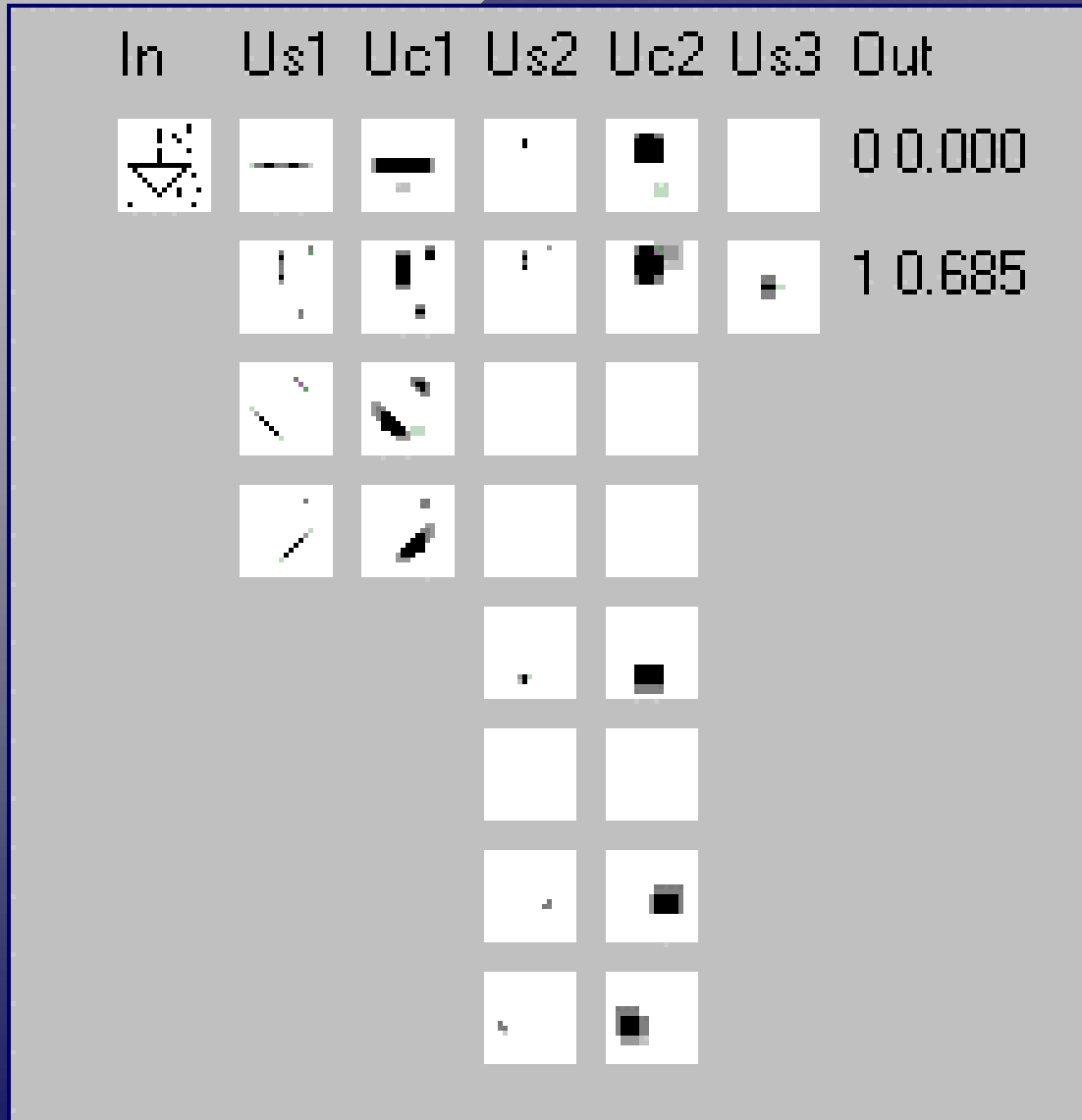
Neocognitron network.

network response on *arrow* images.



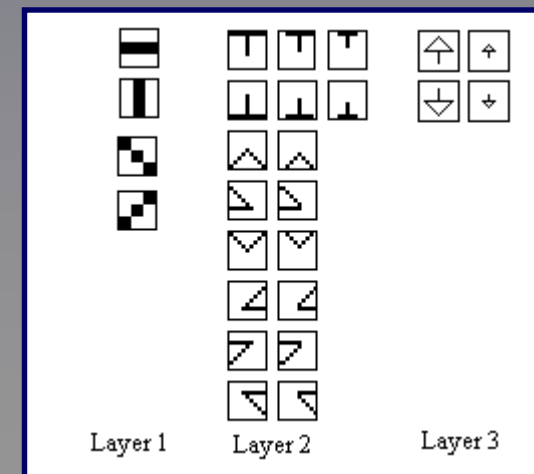
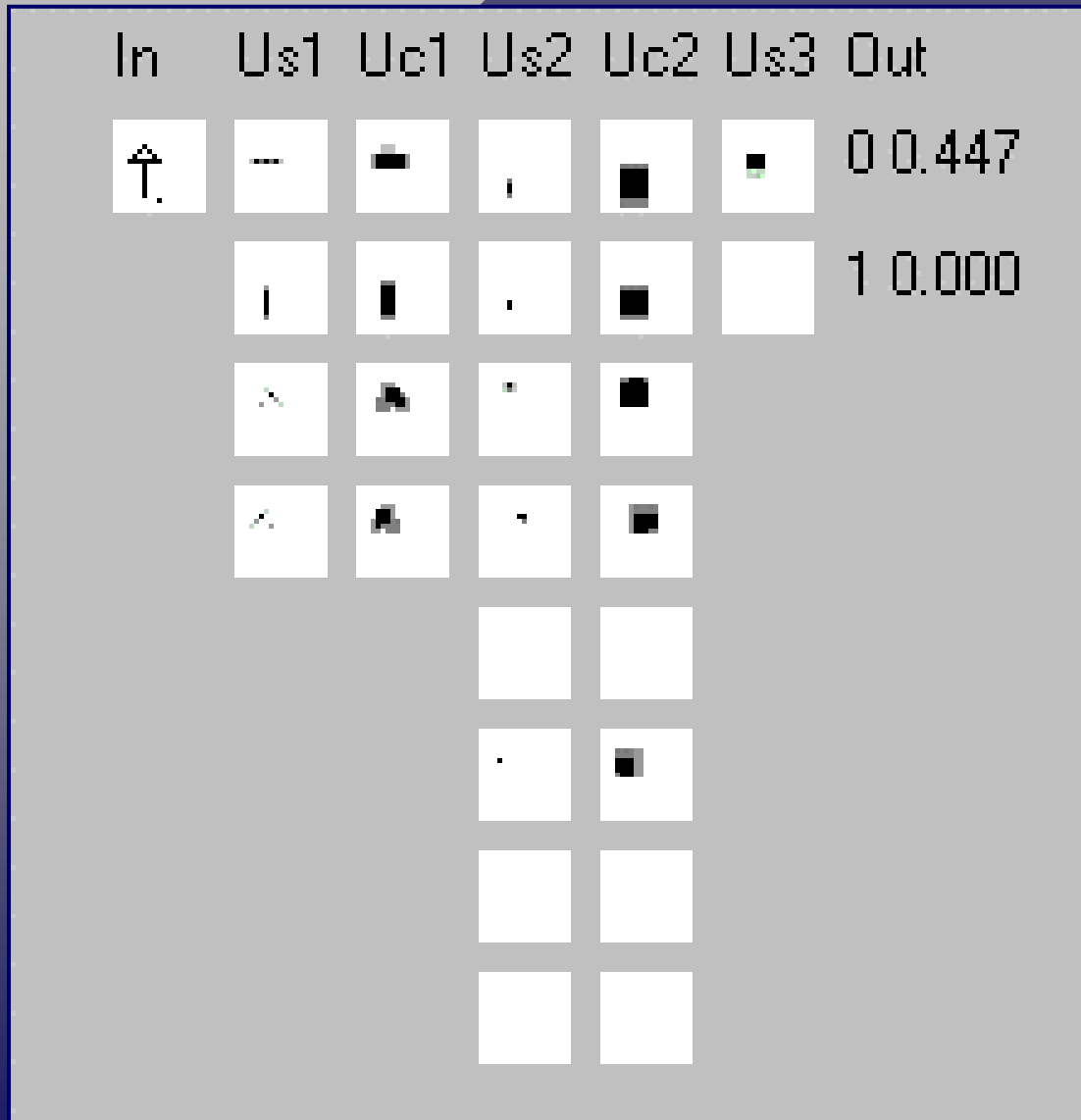
Neocognitron network.

network response on *arrow* images.



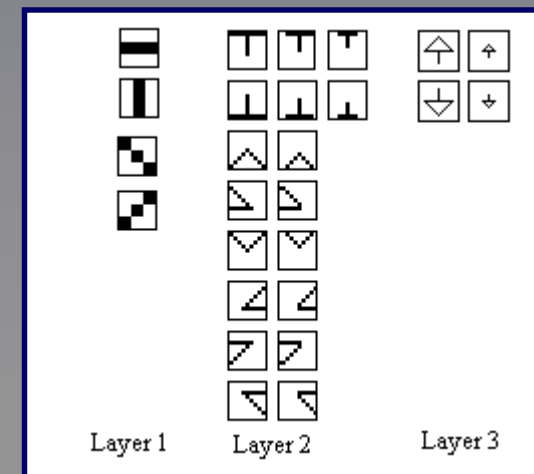
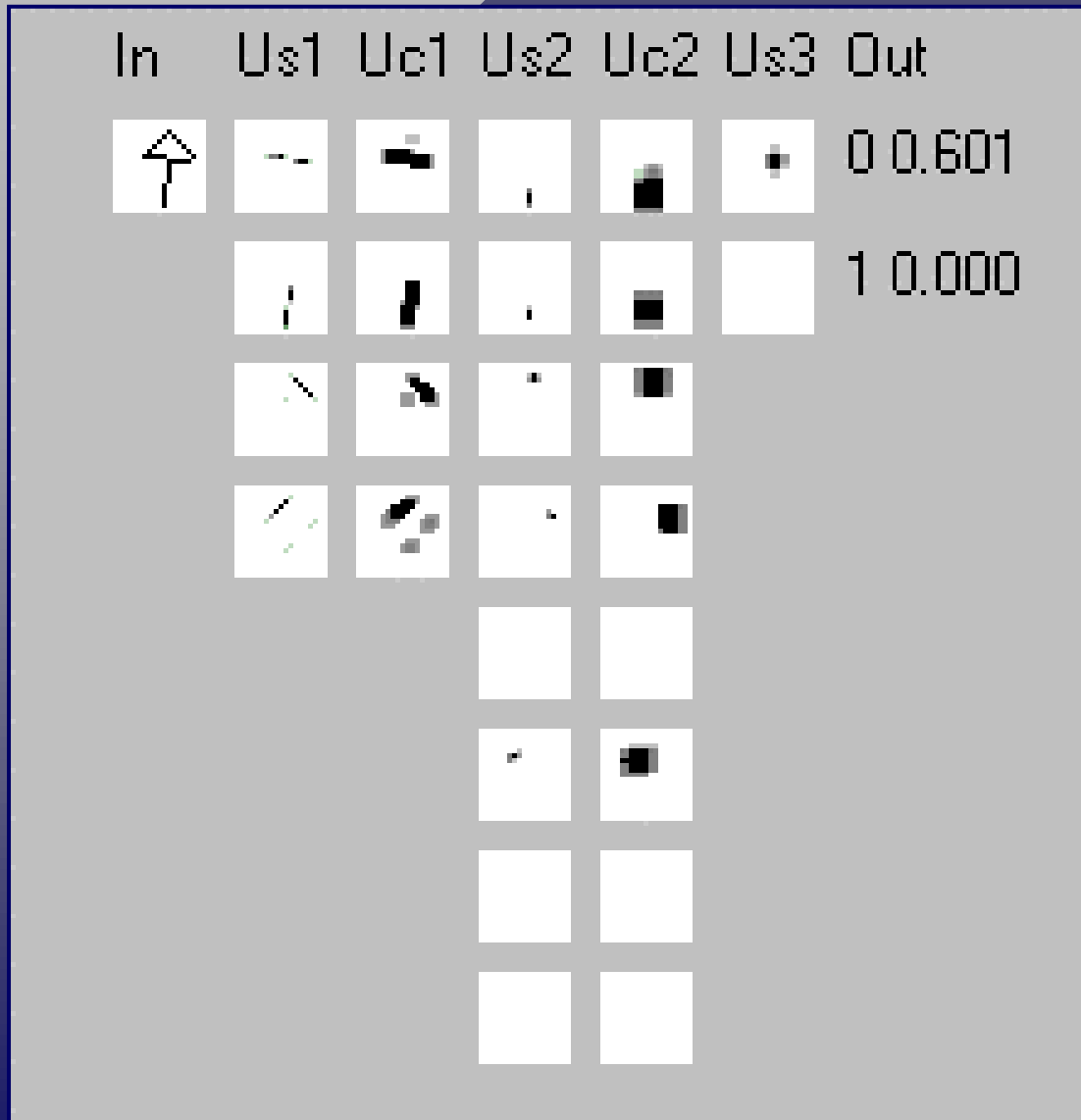
Neocognitron network.

network response on *arrow* images.



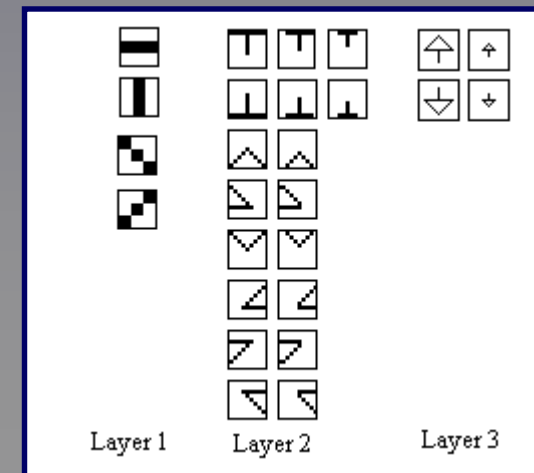
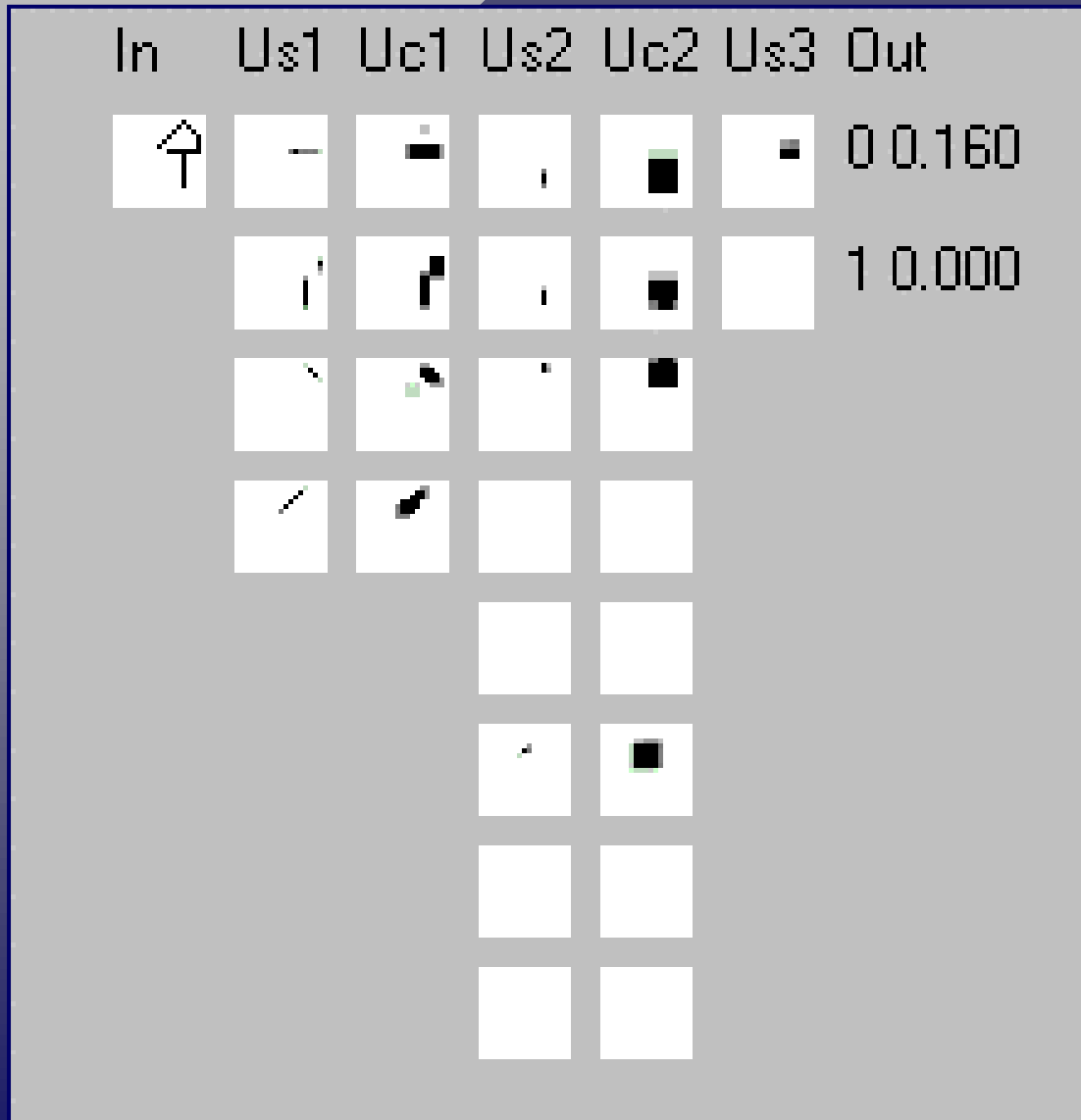
Neocognitron network.

network response on *arrow* images.



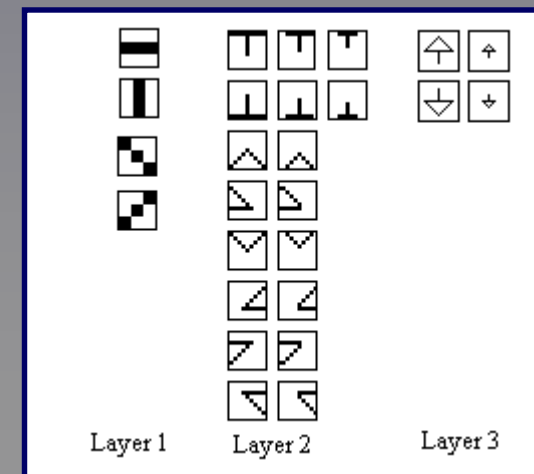
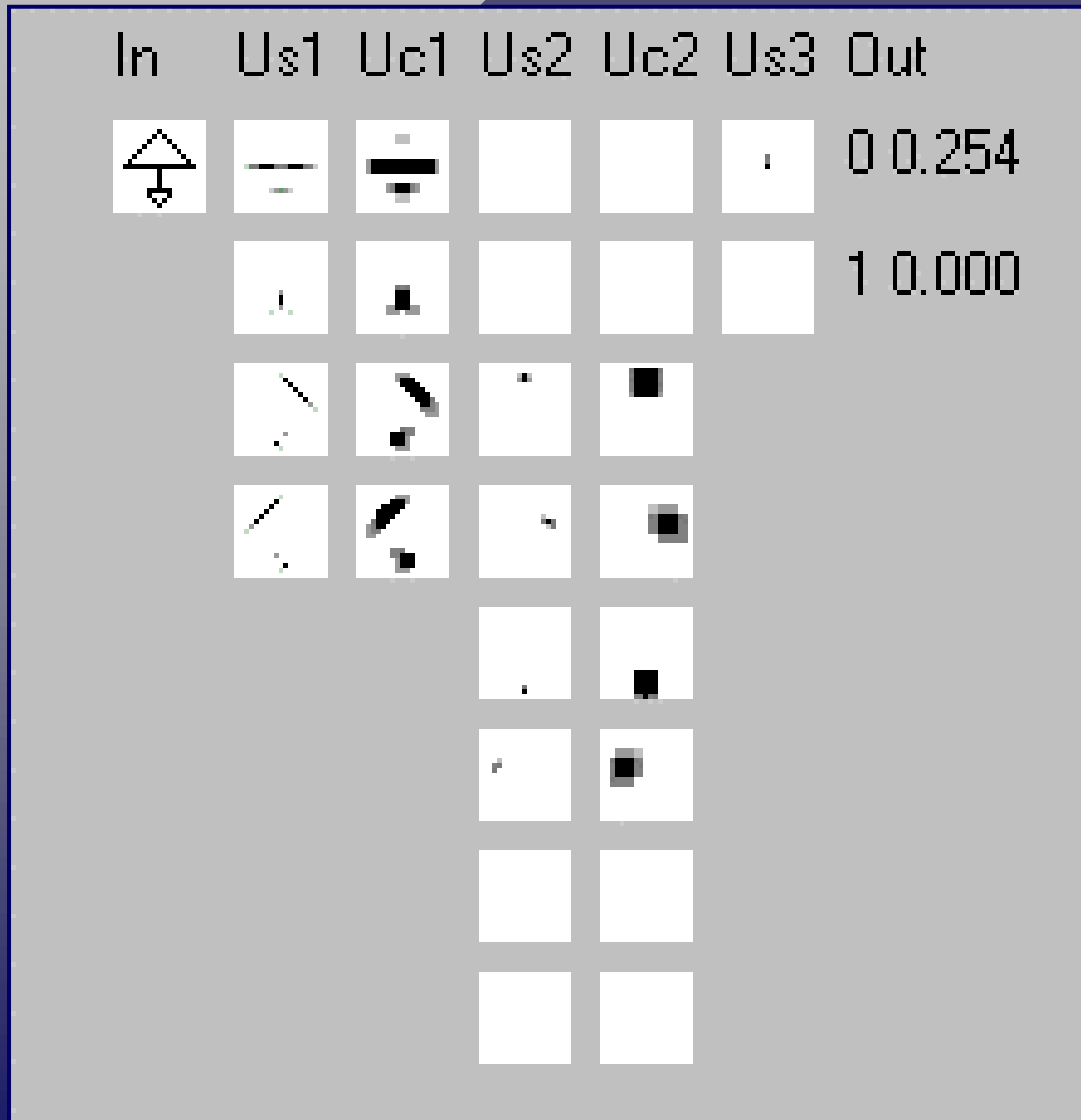
Neocognitron network.

network response on *arrow* images.



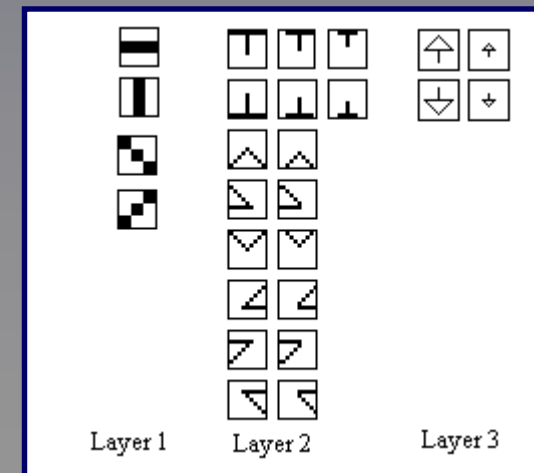
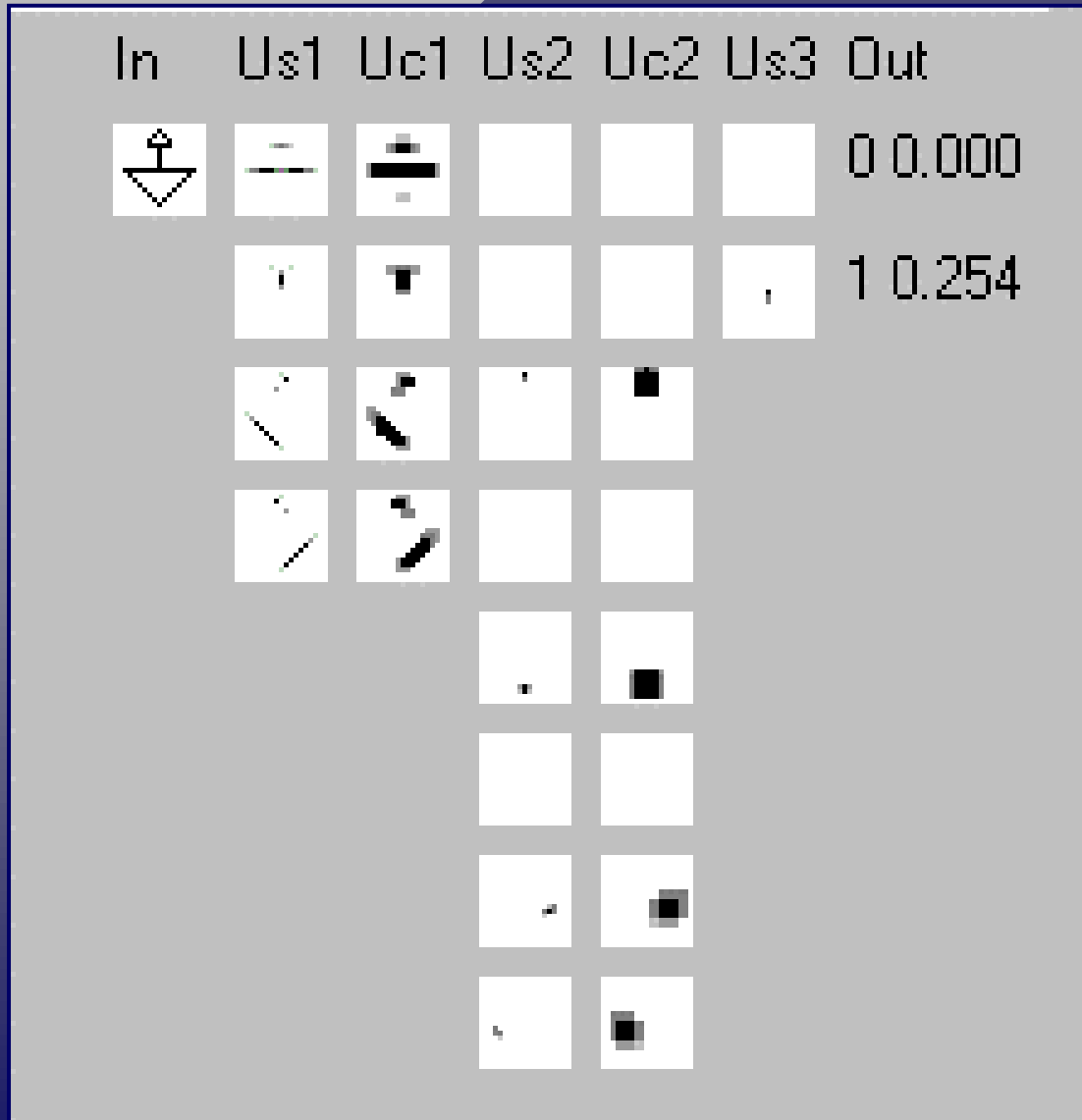
Neocognitron network.

network response on *arrow* images.



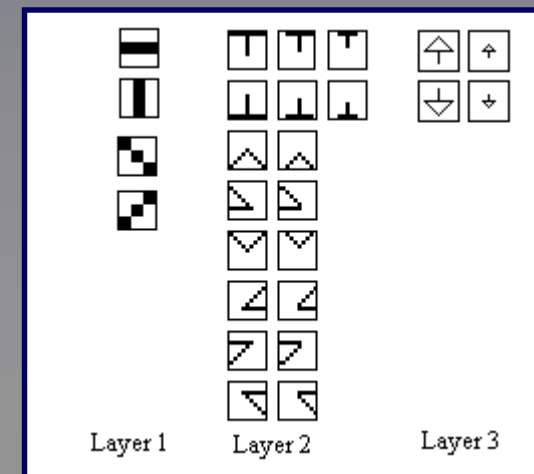
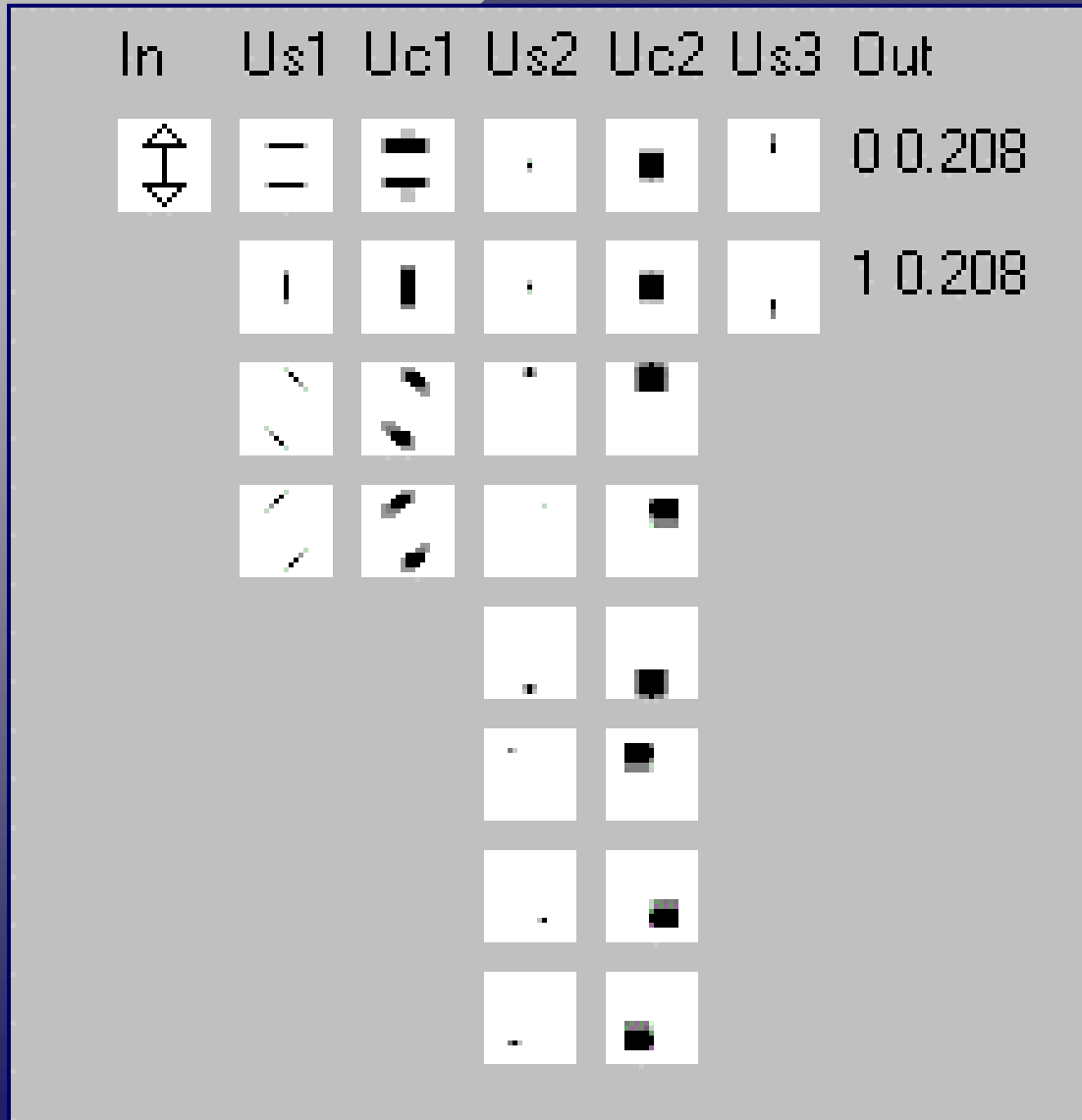
Neocognitron network.

network response on *arrow* images.



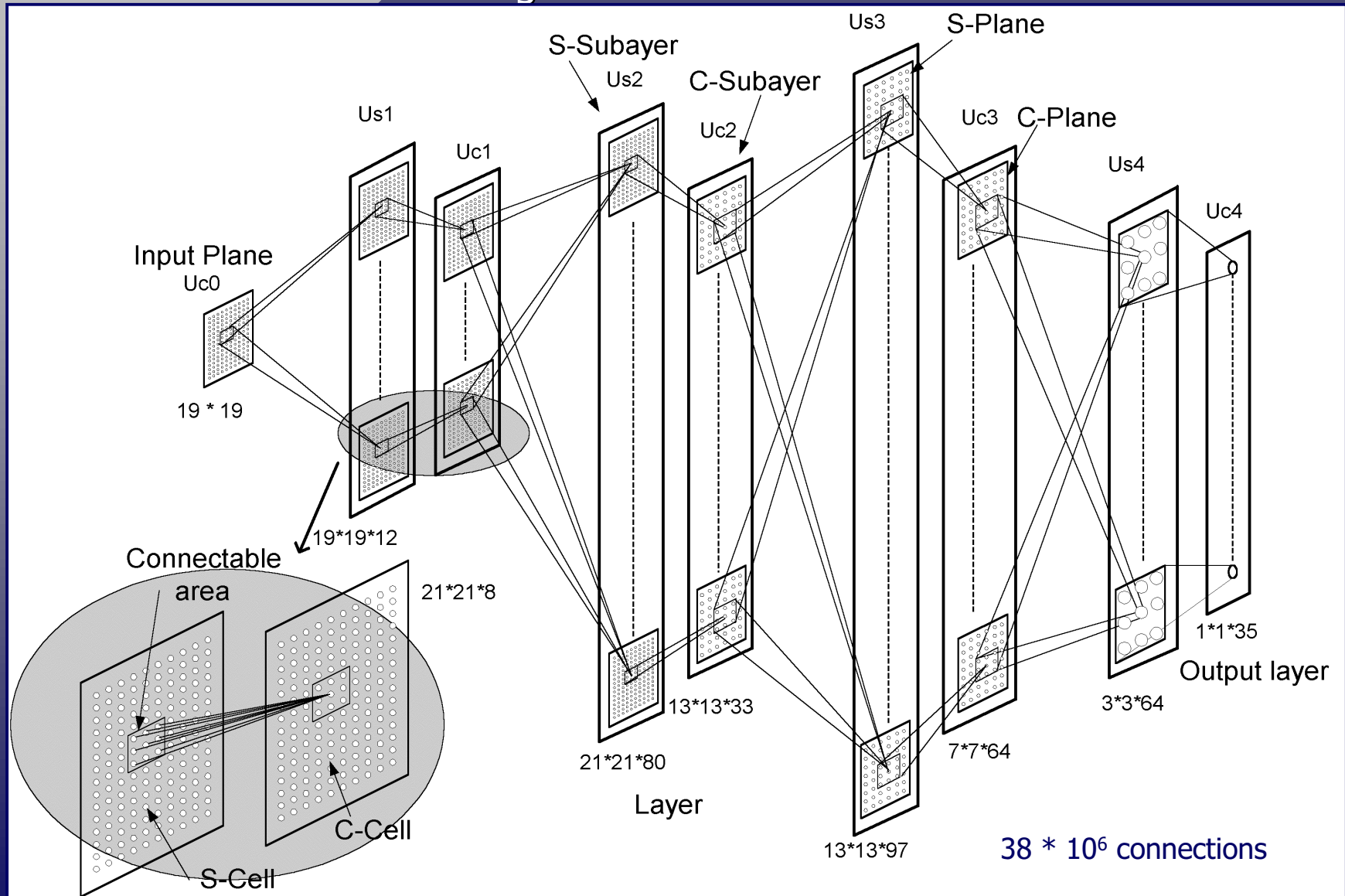
Neocognitron network.

network response on *arrow* images.



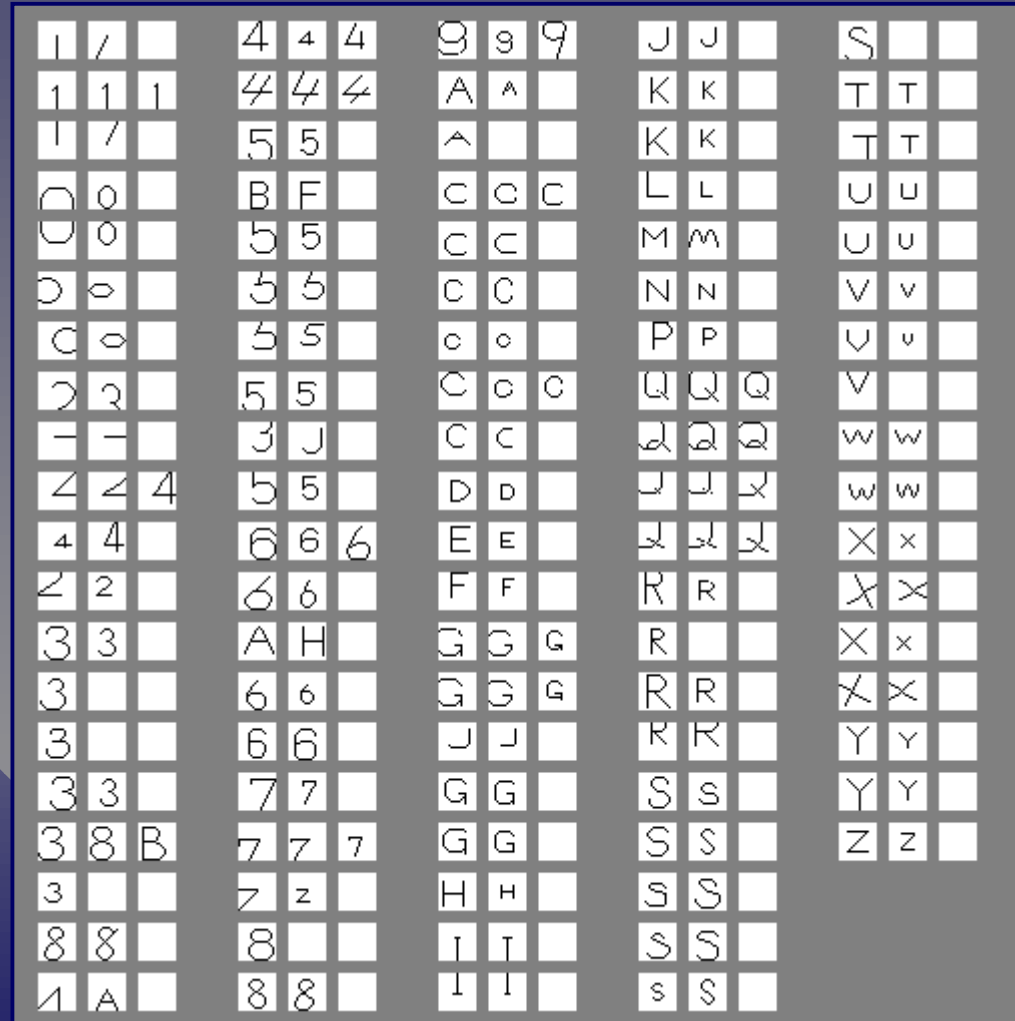
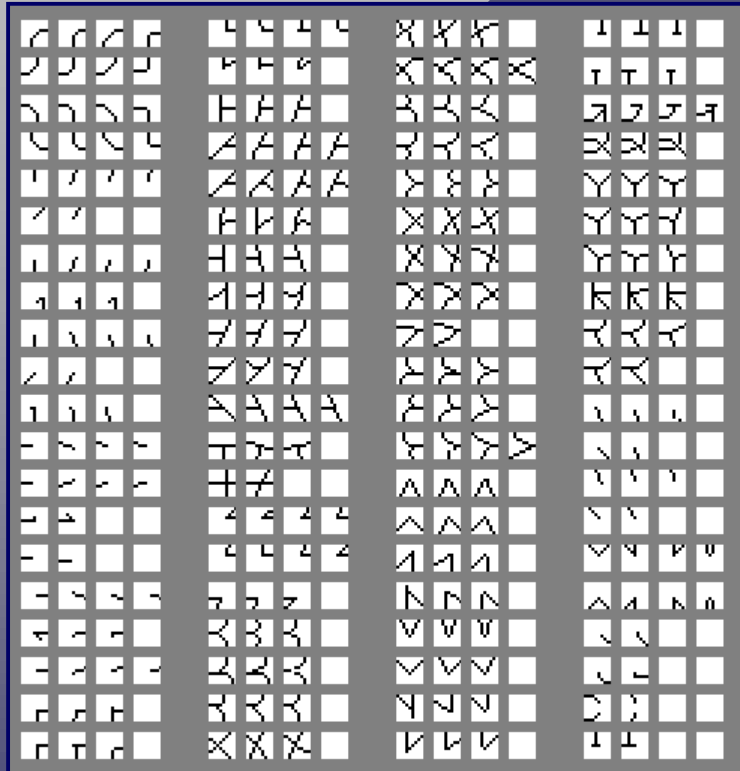
Neocognitron network.

network to recognize handwritten characters.

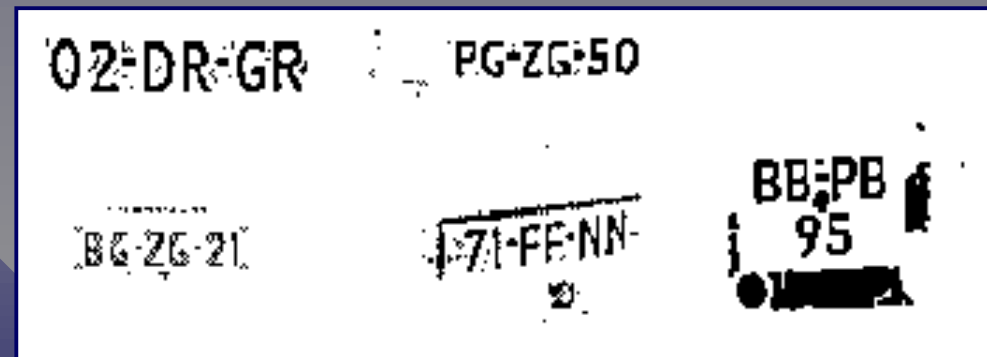


Neocognitron network.

Fukisuma's training set for layer 2 and layer 3



Application neocognitron



Recognition performance

- Network designed to recognize handwritten characters performs **very poor** on printed characters !

Handwritings are a generalisation of printed characters ?

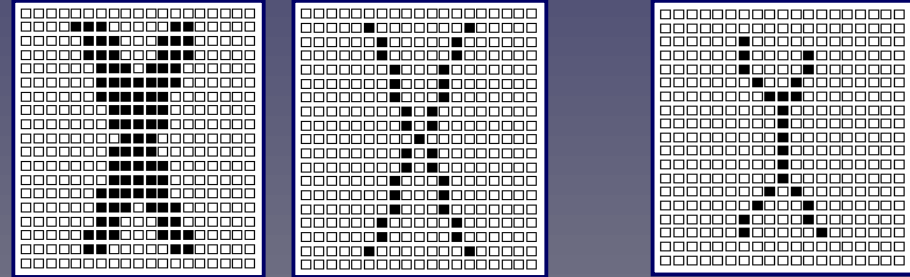
Poor recognition performance caused by ?

Recognizer problems

- Skeletonizer deformation
- Character style
- Ambiguous characters

Recognizer problems

- Skeletonizer deformation



- Character style

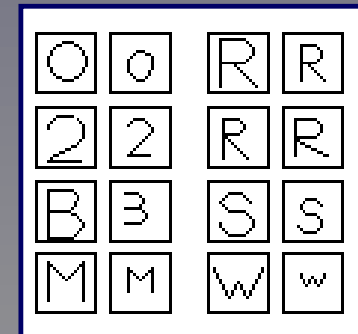
- Ambiguous characters

Recognizer problems

- Skeletonizer deformation

- Character style

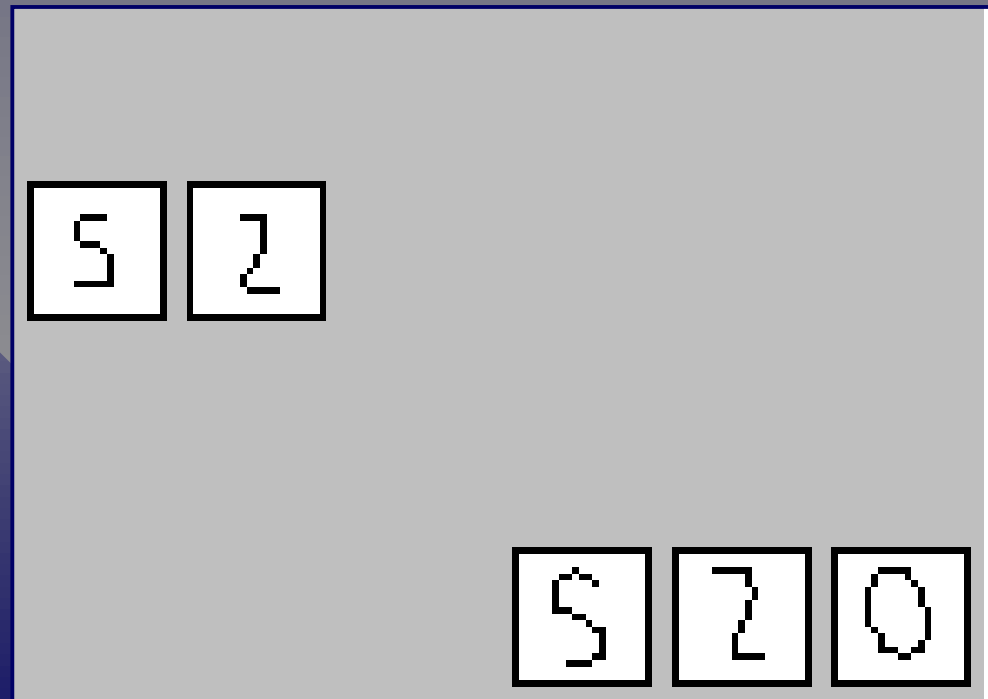
EuroStile font	0	2	B	M	R	S	W
Recognition rate	29%	29%	14%	0%	14%	14%	29%



- Ambiguous characters

Recognizer problems

- Skeletonizer deformation
- Character style
- Ambiguous characters

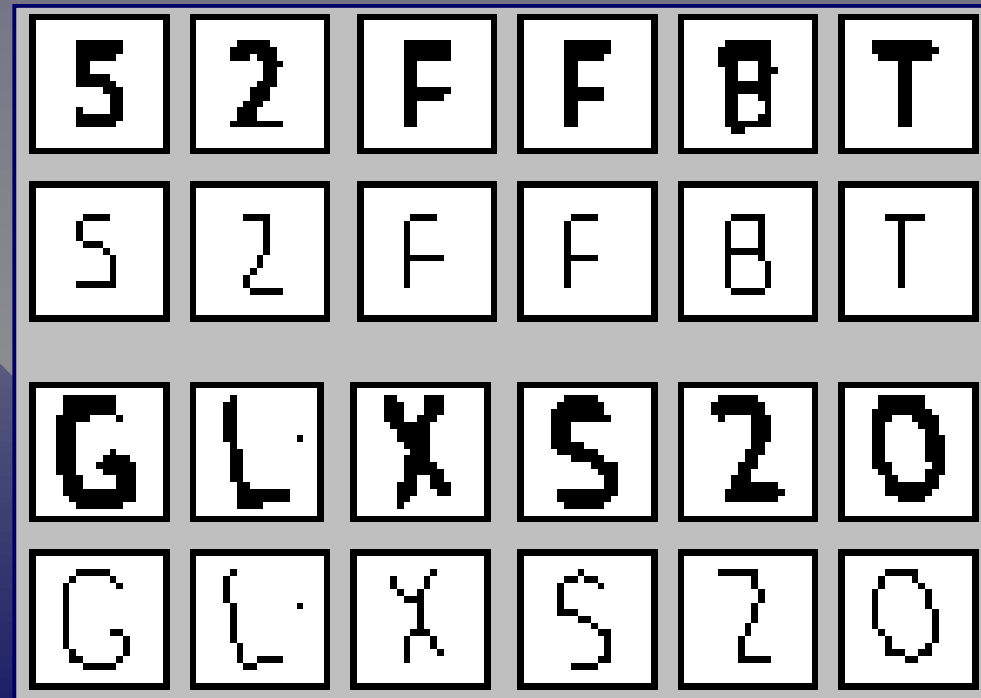


Recognizer problems

- Skeletonizer deformation

- Character style

- *A* ers



Reconfigure the network.

“The optimal scale of the network changes depending on the set of patterns to be recognized. Although it is difficult to show precisely how to choose the network scale parameters, we can offer a few guidelines”

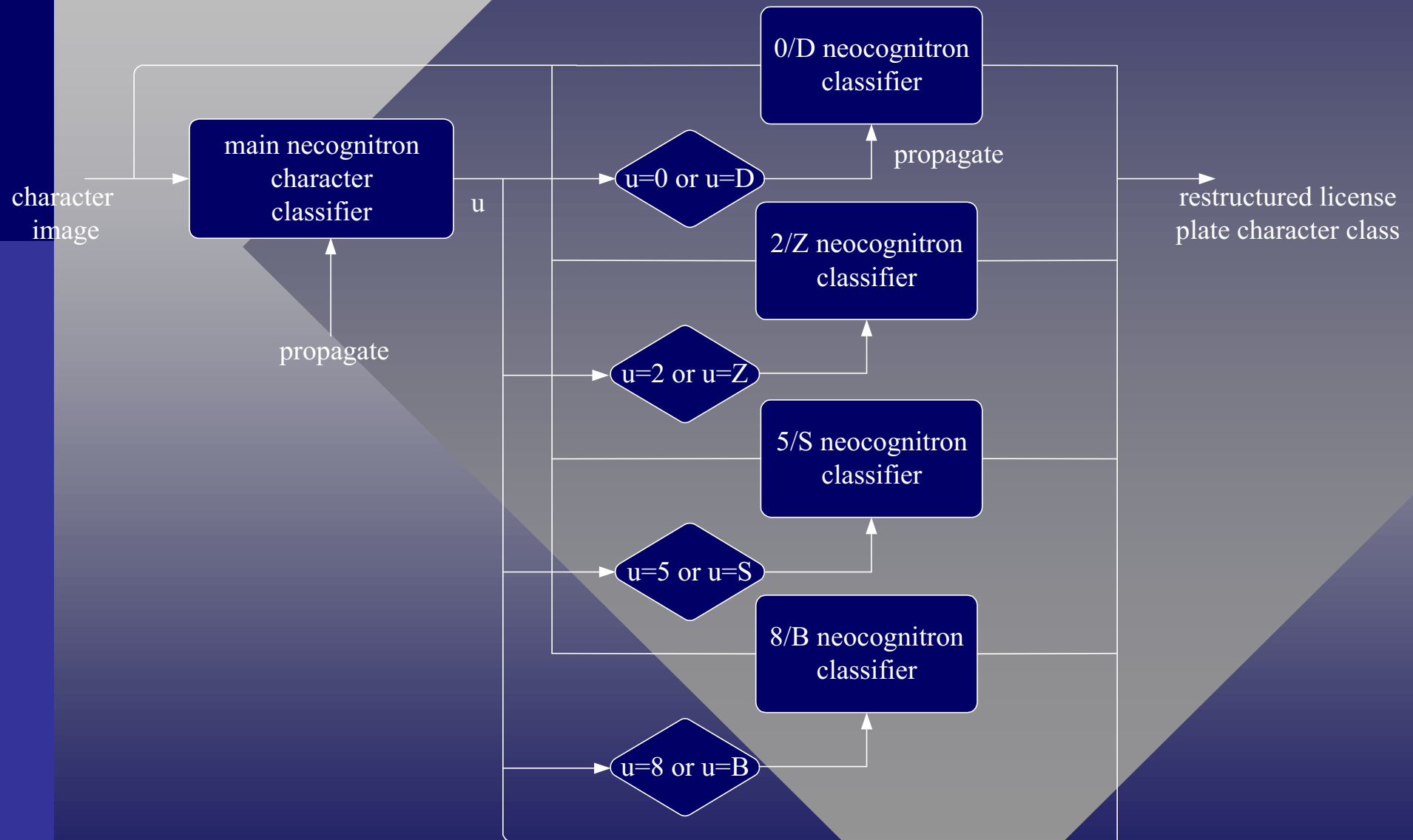
“a process of constructing a good training set requires hard labor with an increase in the number of characters to be recognized”

Fukisuma K. and Wake N. “Handwritten alphanumeric character recognition by the neocognitron”, (1991) *IEEE Transactions on neural networks VOL 2. No 3. May 1991*, pp.355-365.

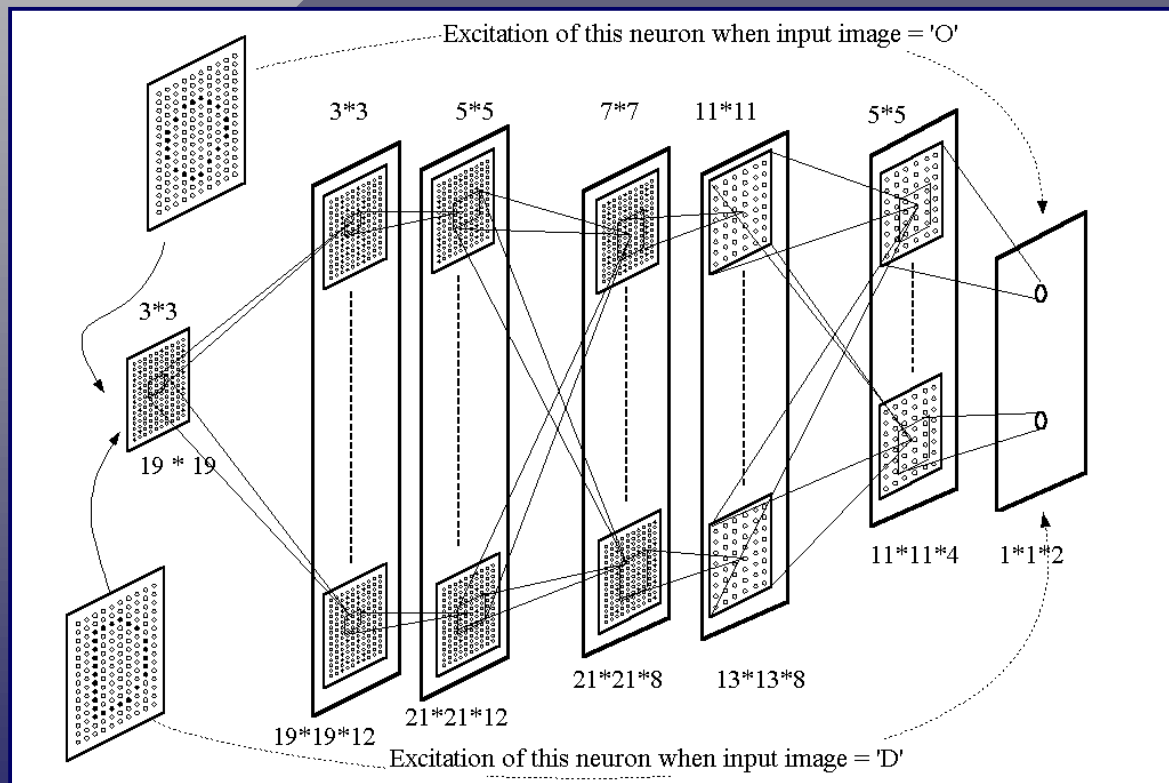
Neocognitron reconfiguring.

- New 3-layer network configuration & new training set patterns to solve skeletonizer deformation and character style incompatibility.
 - Only license plates characters classes
 - Drop location invariance
 - Limitations on size variations
- Specific 3-layer networks for discrimination between ambiguous characters 0/D, 2/Z, 5/S & 8/B.
 - avoid tuning a large network
 - small in size, short training times, easy to tune

Neocognitron specific classifiers



Neocognitron specific 0/D classifier

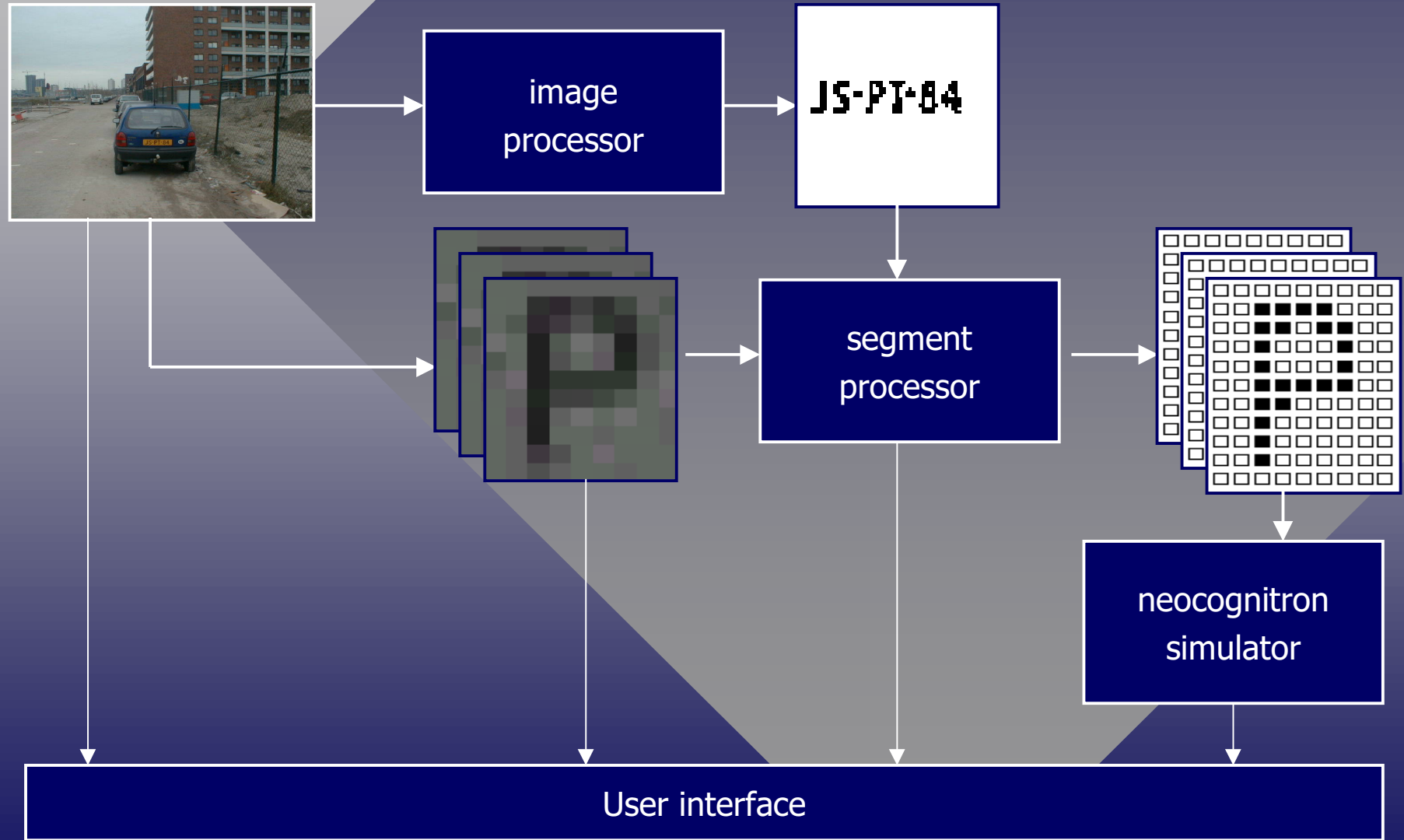


Classified correctly by the reconfigured neocognitron

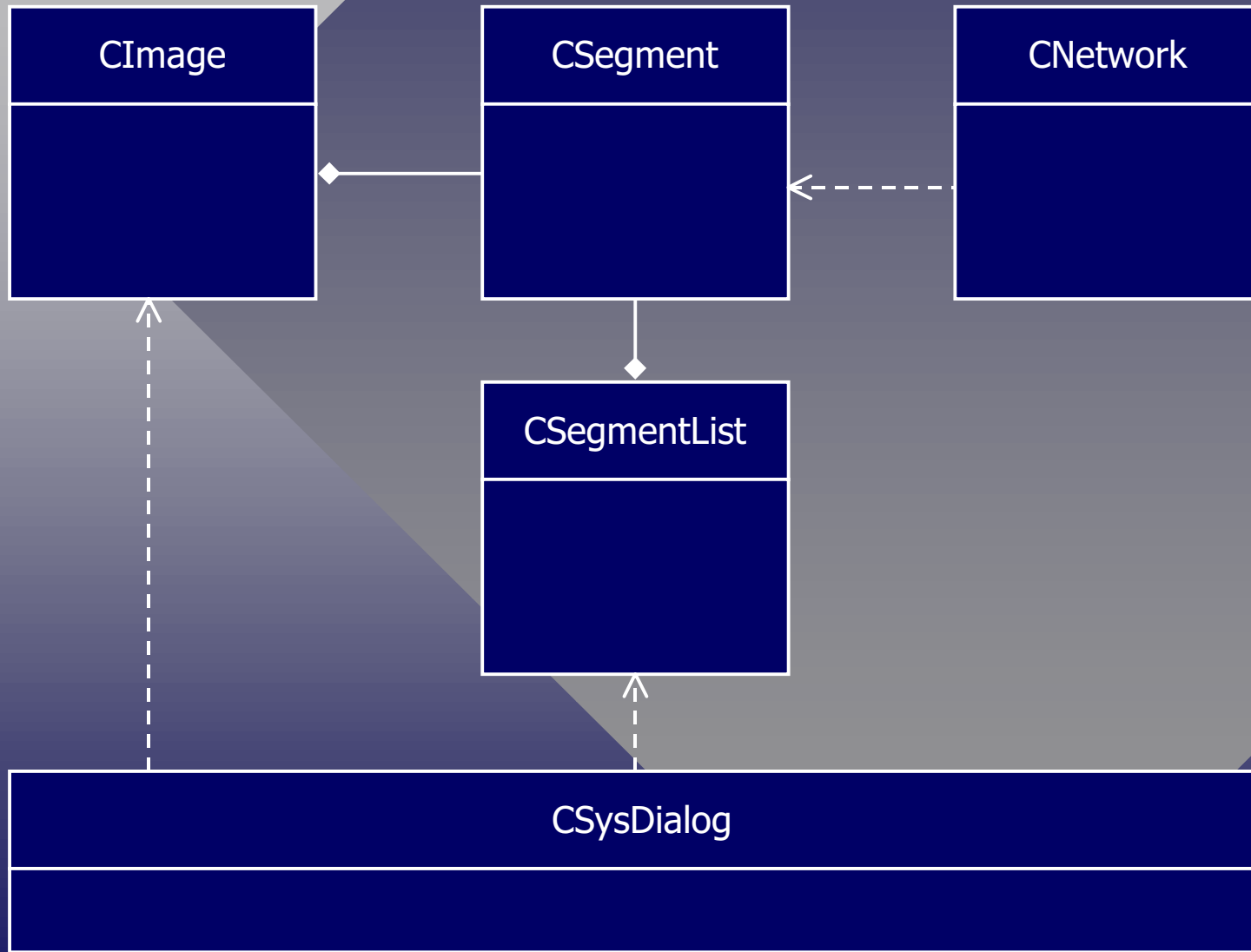
2	T	H	L	L	G	9	P	2	S	Y	P	Y	7	Z	G	T	T	S	4	S	L
2	T	H	L	L	G	9	P	2	S	Y	P	Y	7	Z	G	T	T	S	4	S	L
4	Y	V	X	6	T	O	B	G	K	V	N	L	S	7	0	S	Y	B	D	R	B
4	Y	V	X	6	T	O	B	G	K	V	N	L	S	7	0	S	Y	B	D	R	B
D	3	R	X	8	H	F	R	H	5	8	6	6	S	G	6	4	8	X	8	D	S
D	3	R	X	8	H	F	R	H	5	8	6	6	S	G	6	4	8	X	8	D	S
T	2	H	H	G	1	N	B	7	8	8	8	8	F	F	S	3	8	3	P	J	R
T	2	H	H	G	1	N	B	7	8	8	8	8	F	F	S	3	8	3	P	J	R
V	D	3	9	B	5	T	2	R	L	X	4	D	S	N	R	L	D	6	H	2	P
V	D	3	9	B	5	T	2	R	L	X	4	D	S	N	R	L	D	6	H	2	P
N	Y	8	6	P	X	P	6	T	D	R	B	R	L	S	G	D	Y	J	4	7	J
N	Y	8	6	P	X	P	6	T	D	R	B	R	L	S	G	D	Y	J	4	7	J

Character level 94 % recognition

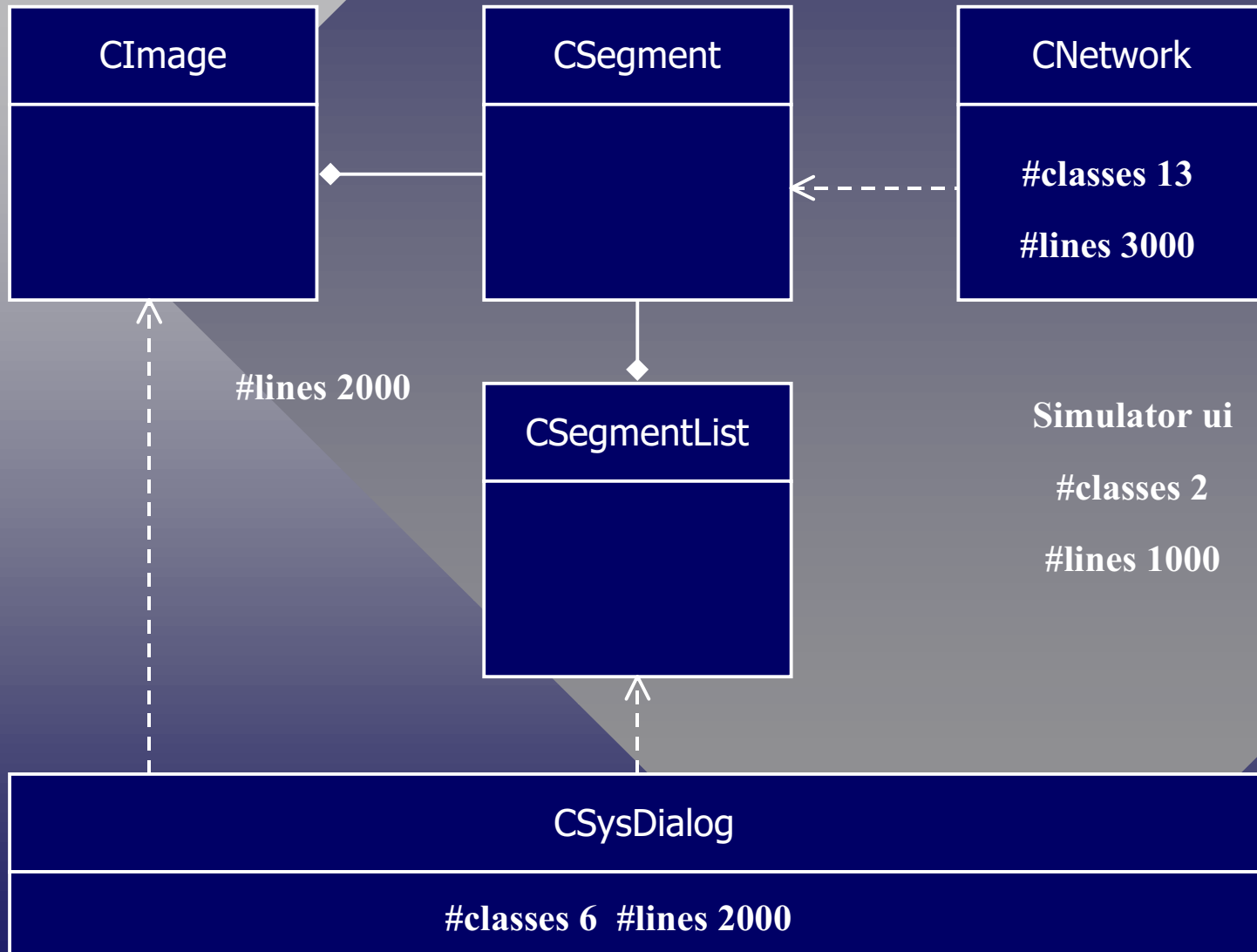
CLPR conceptual diagram



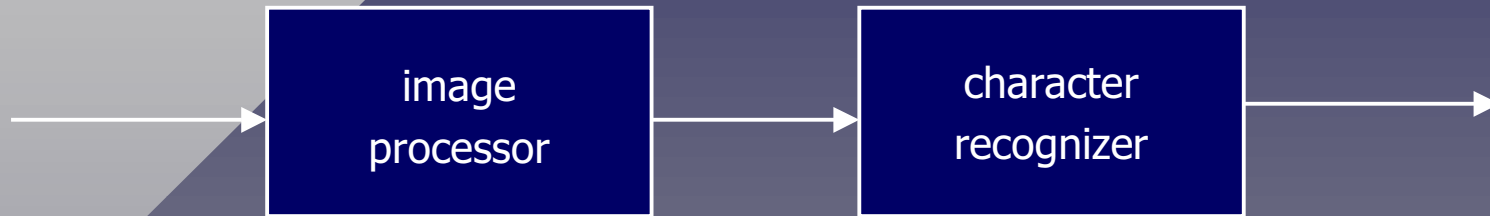
CLPR class diagram



CLPR class diagram



CLPR evaluation.



- Image processor
 - successfully isolating all plate character : 87 %
- Character recognizer
 - correctly classifying an isolated character : 94 %
 - correctly reading a number plate : 73 %

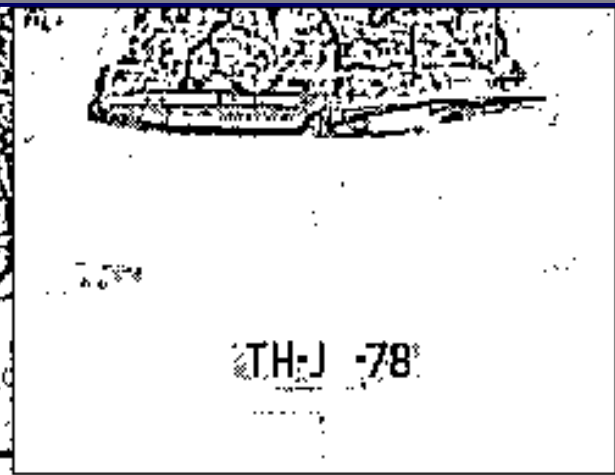
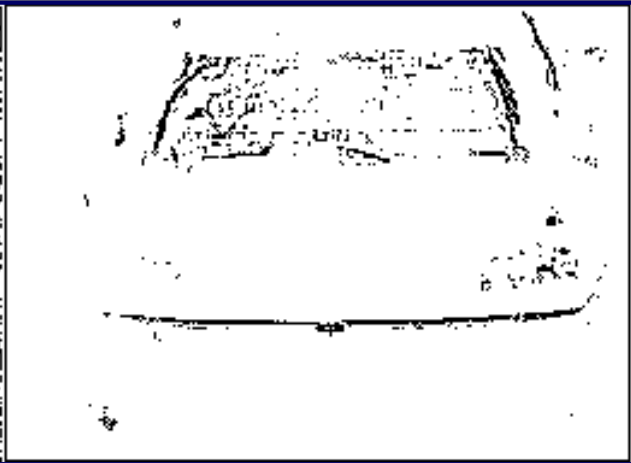
CLPR failures

Image processor **13% loss**



CLPR failures

Image processor **13% loss**

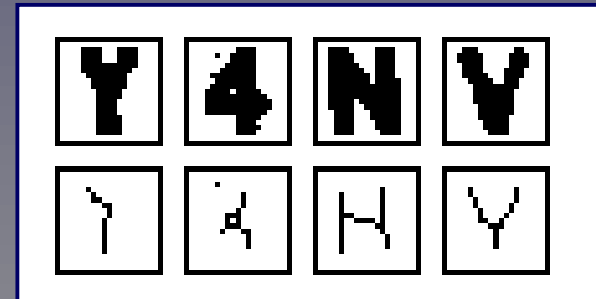


CLPR failures

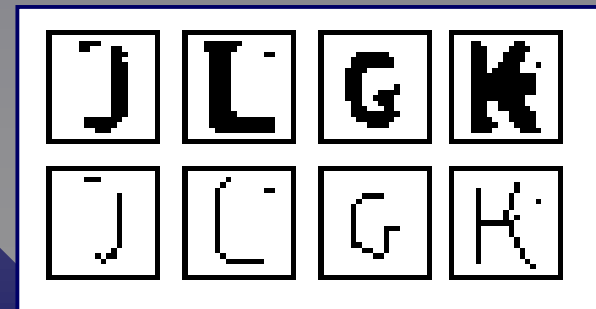
Recognizer **6% loss**

- 0/D, 2/Z, ..., 8/B misclassifications

- Skeletonizer



- Network



Conclusion

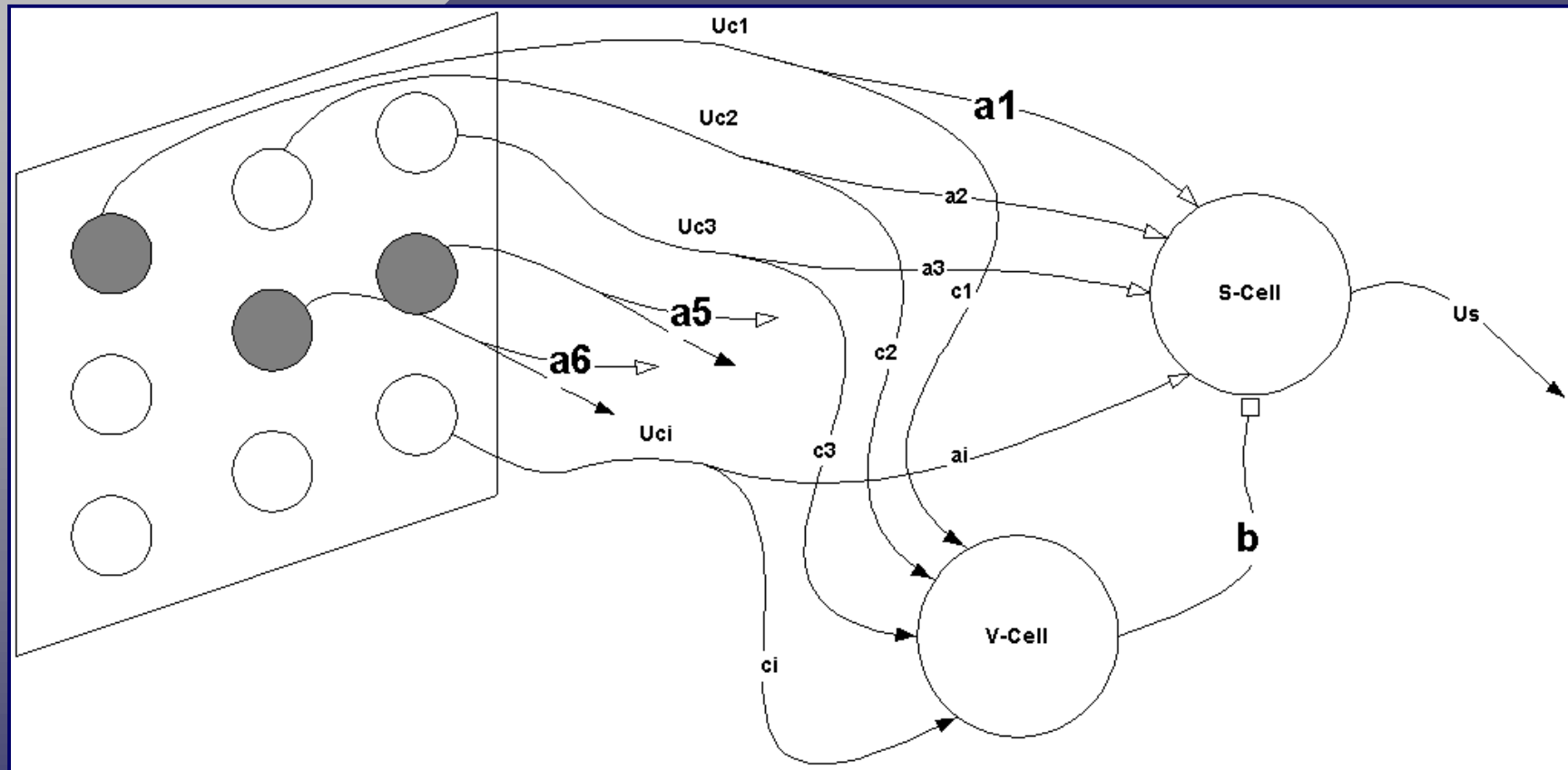
- CLPR system characteristics
 - 65% overall performance
 - down to 10 pixel character sizes. Location, size & color invariant
- Processing Improvements
 - recognizer 73% → 95%
 - post processing using syntax forcing (≈10 %),
 - skeletonizer and neocognitron configuration/training (≈10 %)
 - pre-processor 87% → 95%
- 90% should be achievable using this concept

neocognitron
simulator

CLPR
prototype

Neocognitron network.

network training.



$$\Delta a_{\lambda}(v, \kappa, \rho) = q_{\lambda} c_{\lambda}(v) U c_{\lambda-1}(\eta + v, \kappa)$$

$$\Delta b_{\lambda}(\rho) = q_{\lambda} U v_{\lambda-1}(\eta)$$